

Overview

- Drones & FPV
- Vehicular Keyless Entry
- Multi-path



Drones & FPV

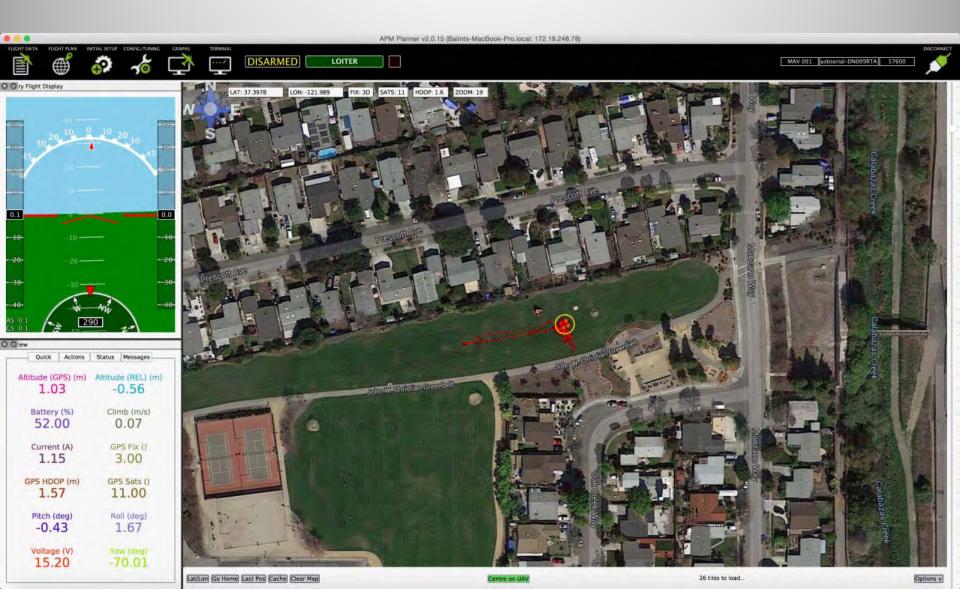
Hacking the Wireless World with #sdr

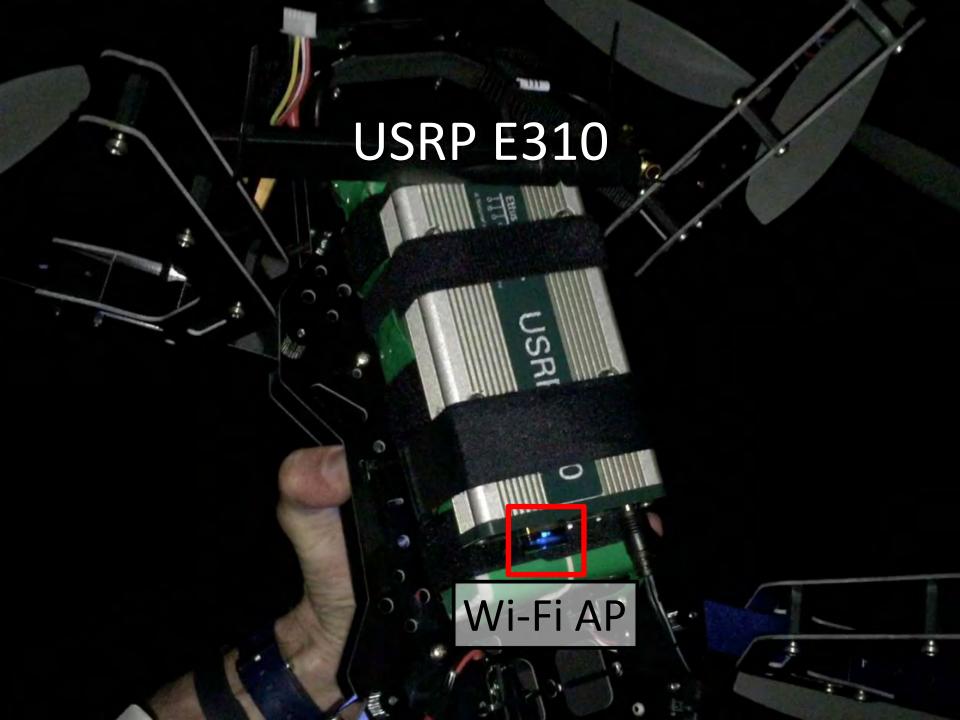
@spenchdotnet





Live Telemetry





FPV





Projects News Videos Events Contests Shop Publications

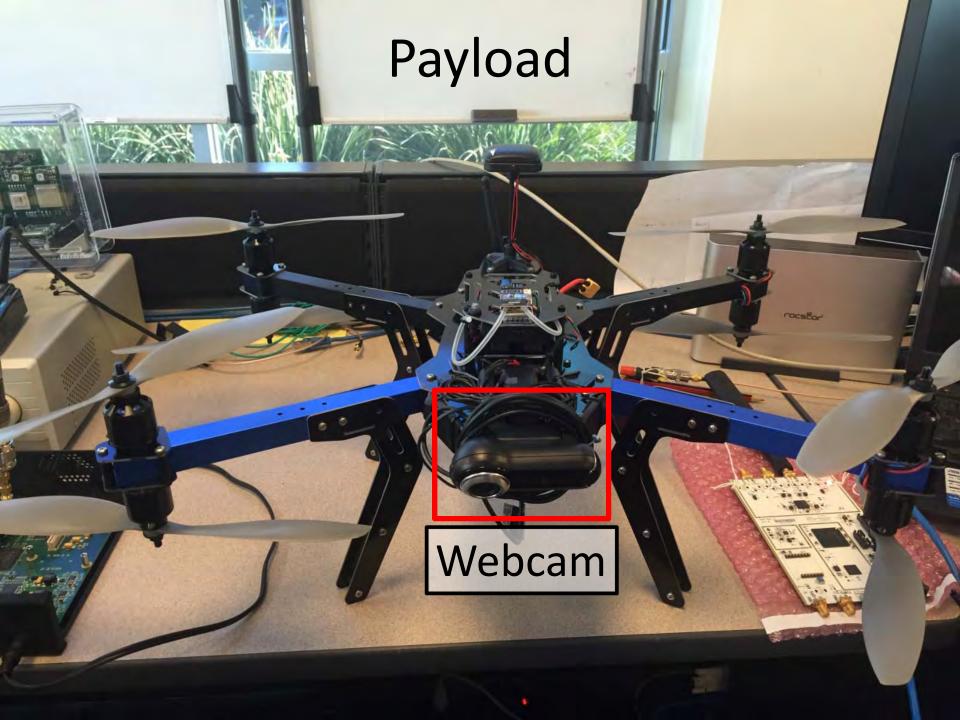
Find your DIY supplies in the Maker Shed → Kits, Books, Components, 3D Printers, Arduino, Raspberry Pi, More!

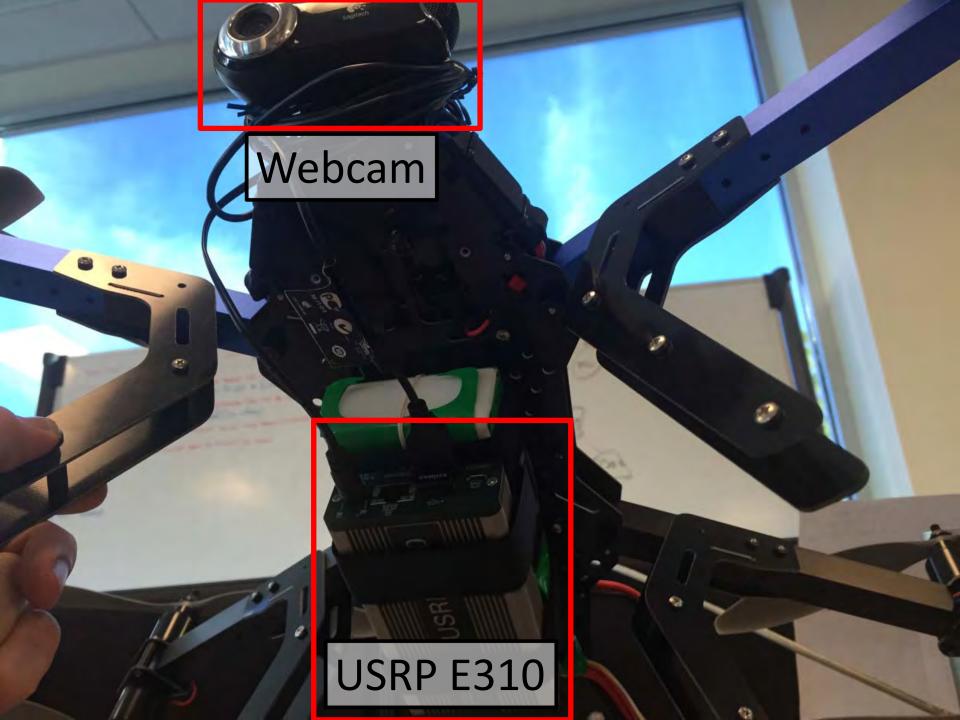
SHOP NOW

Frequency Management: Don't Wreck Your Neighbor's Drone

By Tyler Winegarner March 3rd, 2015 3:12 pm Category Electronics, Robotics







System Components

Transmitter

- Image acquisition
- Packetisation & framing
- Modulation

Receiver

- Demodulation
- Deframing
- Image display

Image Acquisition

- v4l: Video for Linux
- Webcam
 - Raw
 - MJPEG: Motion JPEG
 - (H264 on C920)
- Python: python-v4l2capture
- Get image buffer



Packetisation & Framing

Entire image buffer

Segment to MTU



Add fragment header

Frame/image info

Fragment offset



Add frame header

Payload length

CRC

Frame structure

Packet

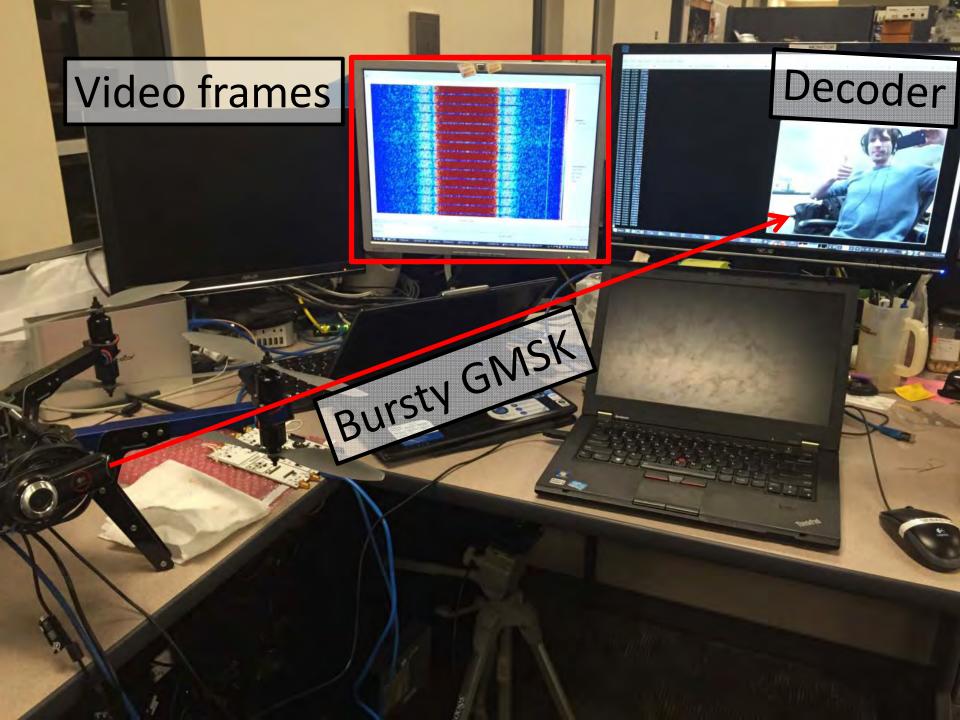
- Preamble
- Access code
- Length
- Whitener index
- CRC

Image fragment

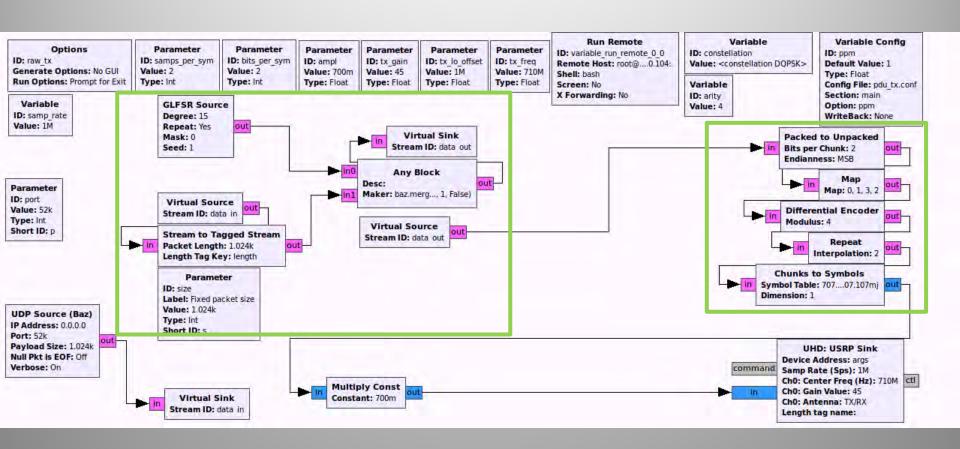
- FOURCC
- Resolution
- Sequence #
- Total frame size
- Fragment length
- Offset

Payload

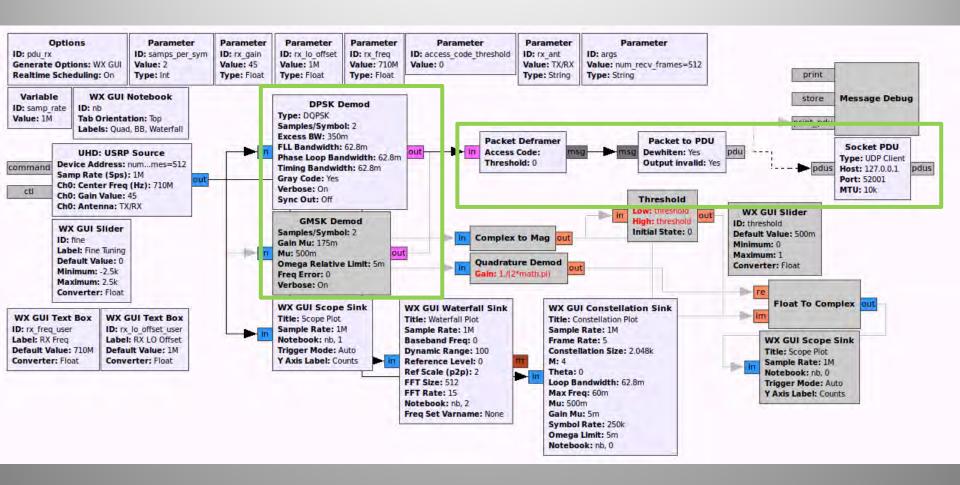
• Image fragment



TX Flowgraph



RX Flowgraph



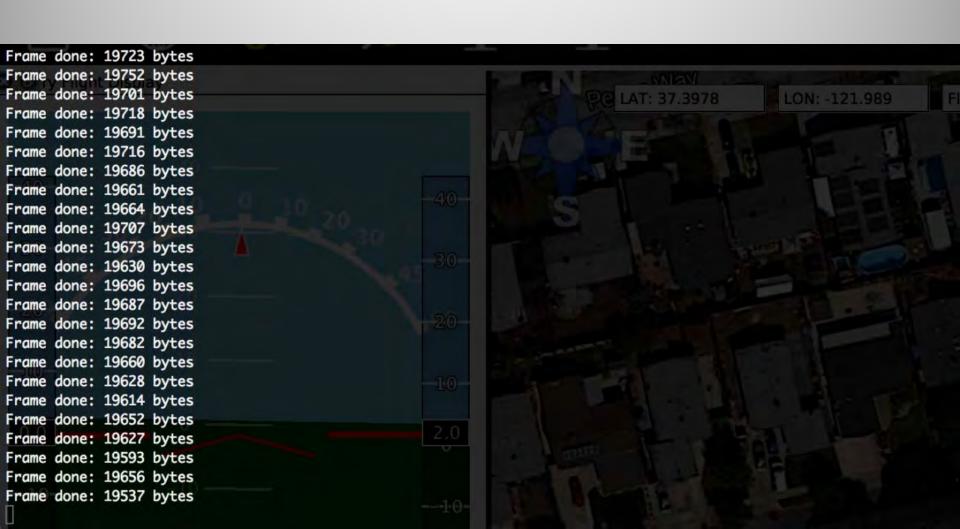
First Outdoor Test



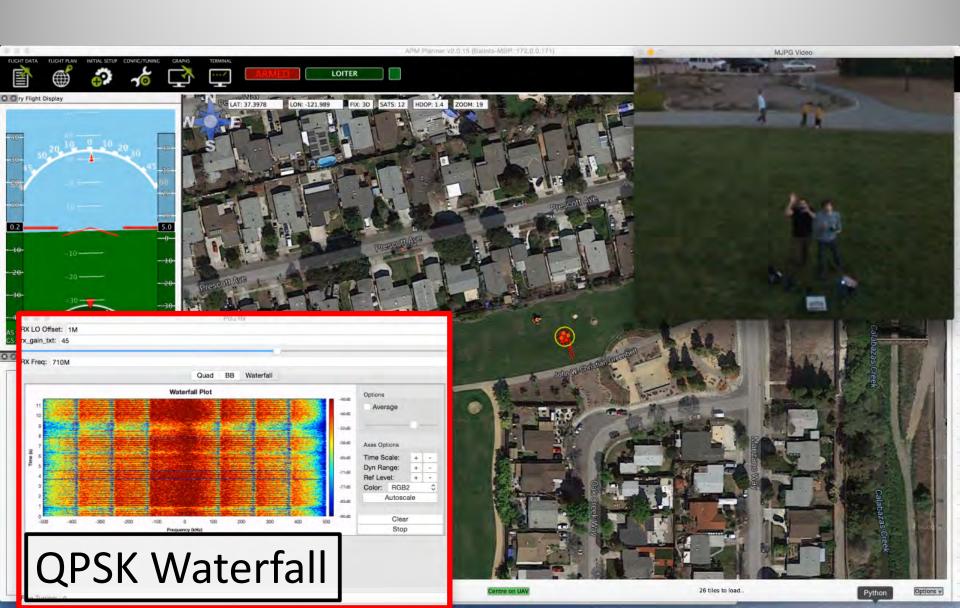
First Outdoor Test



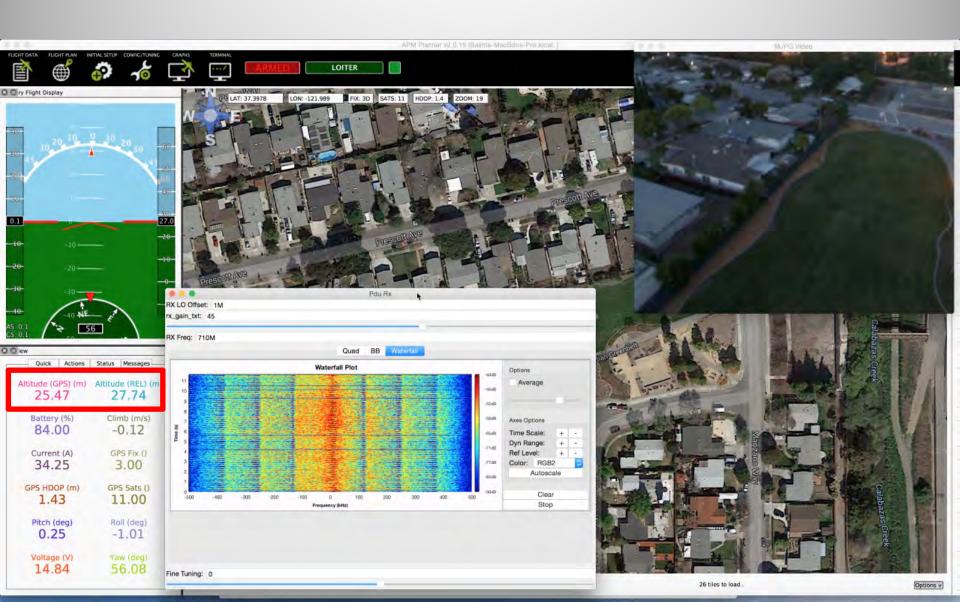
Frame Packet Parser



Wave to the Drone!



View from Above

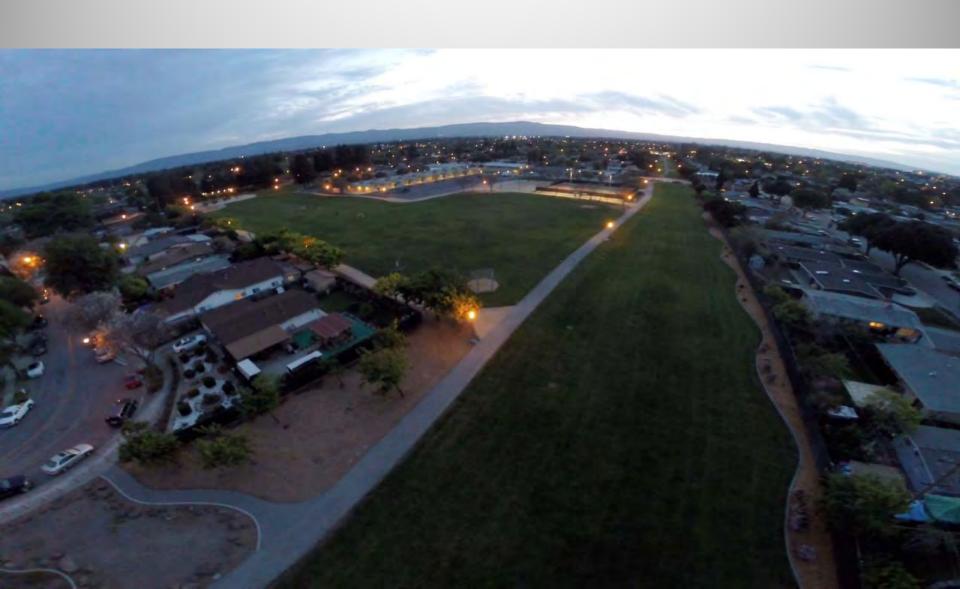




View from Above

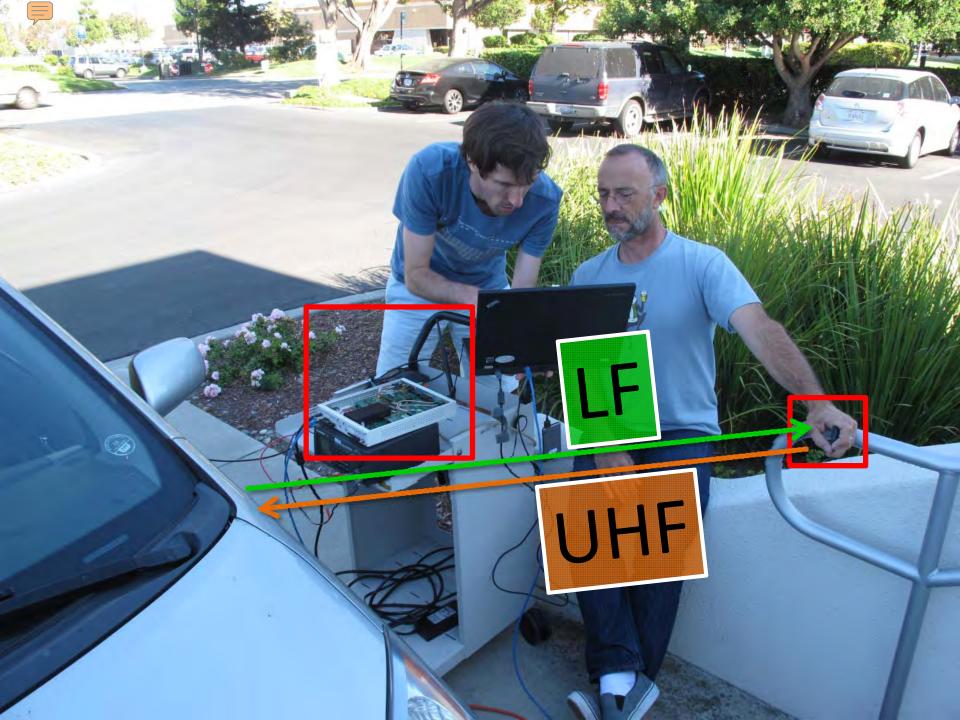


View from Above

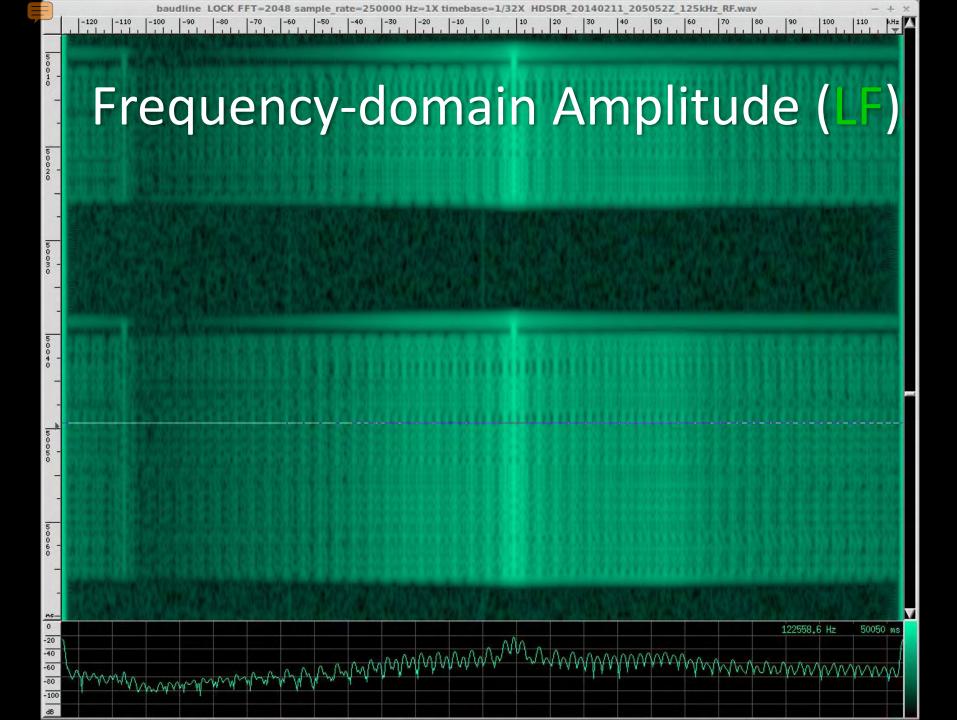






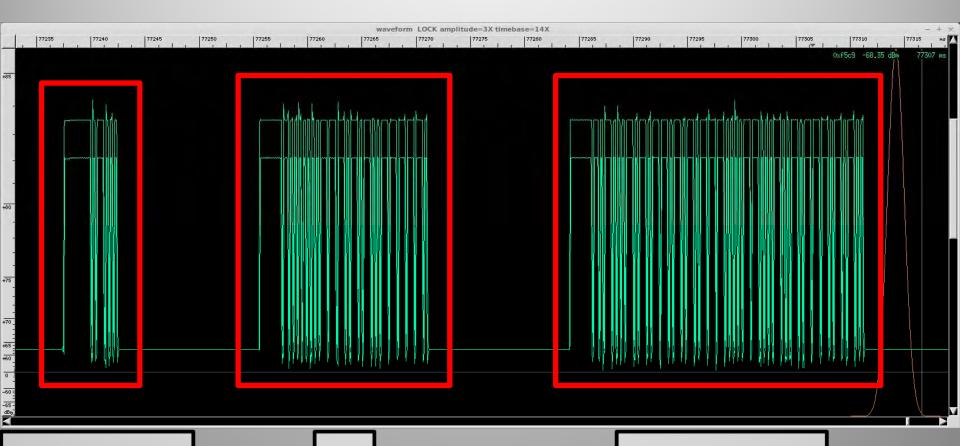








Time-domain Amplitude (LF)



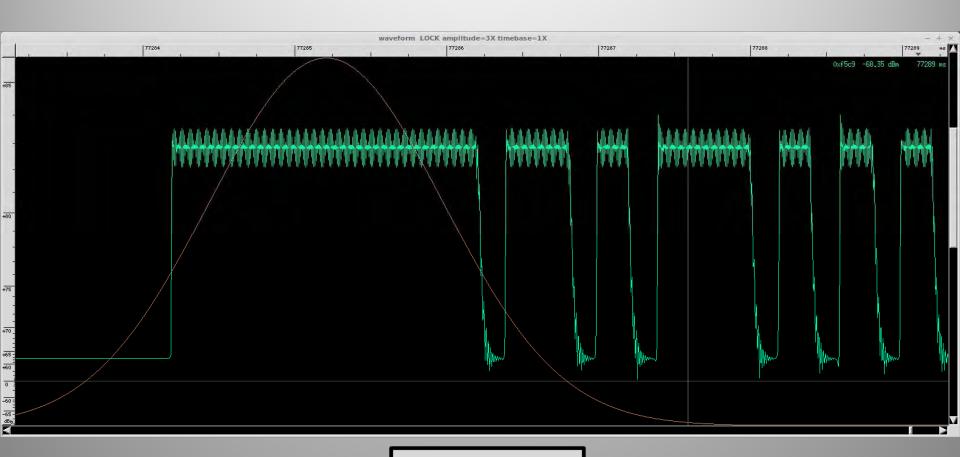
Wake-up

ID

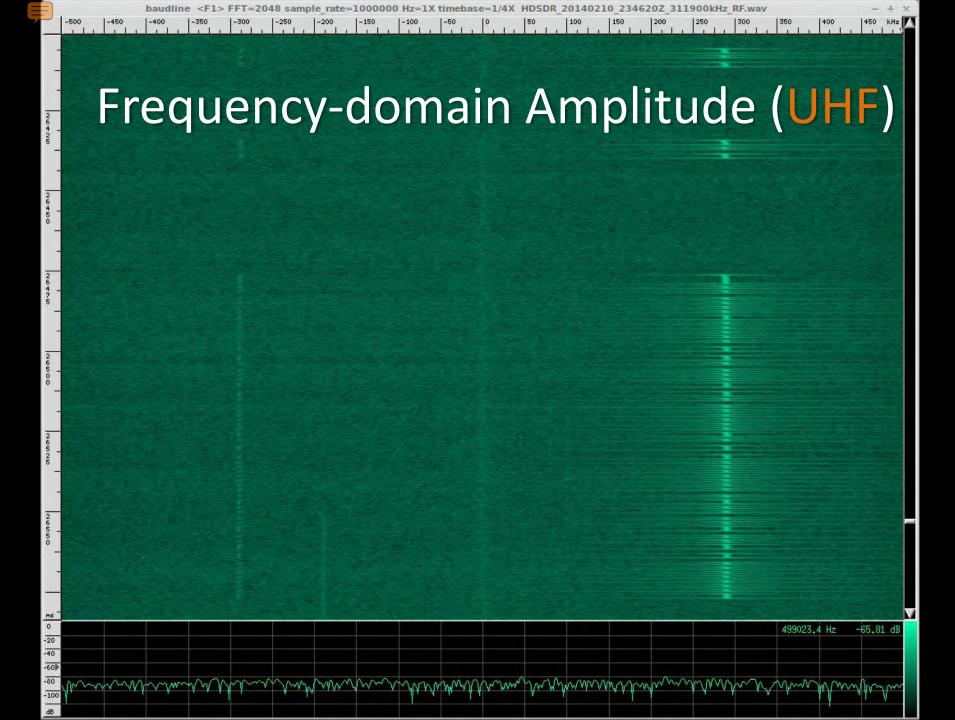
Challenge



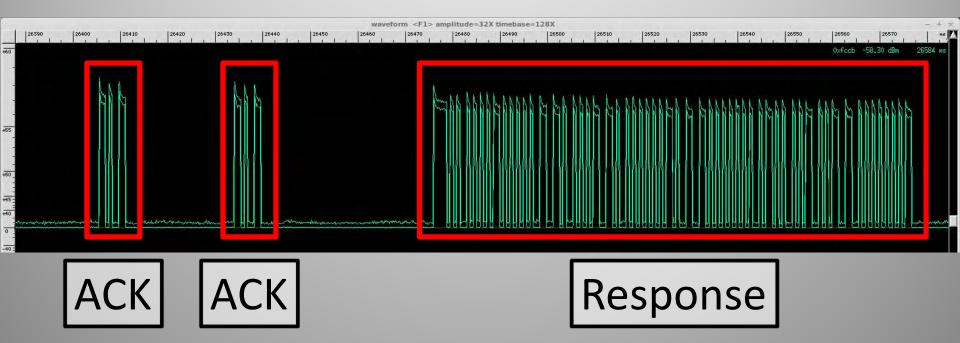
Time-domain Amplitude (LF)

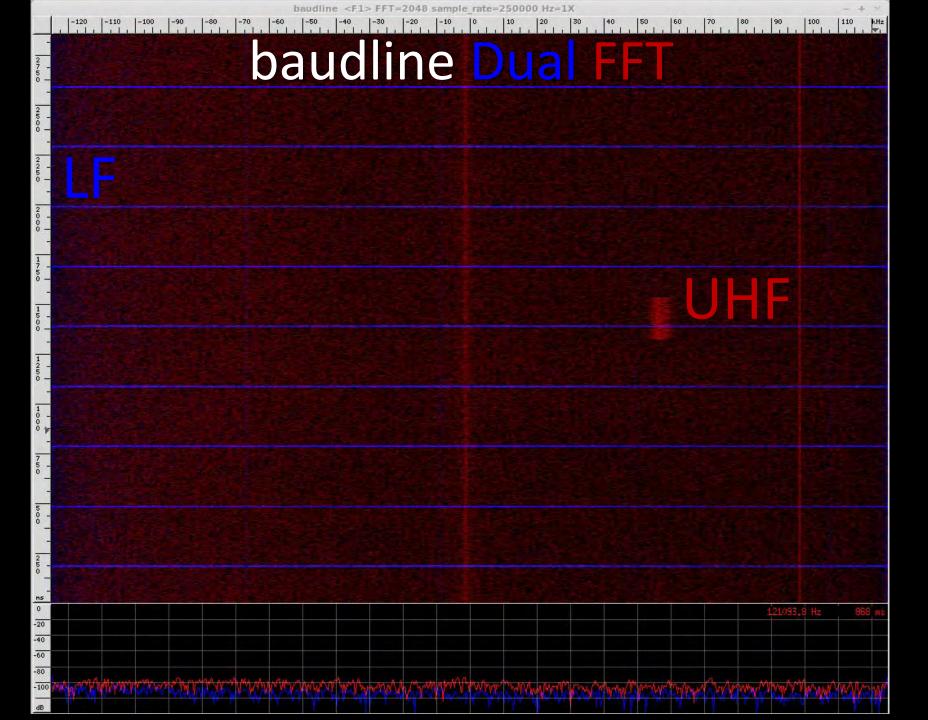


Wake-up

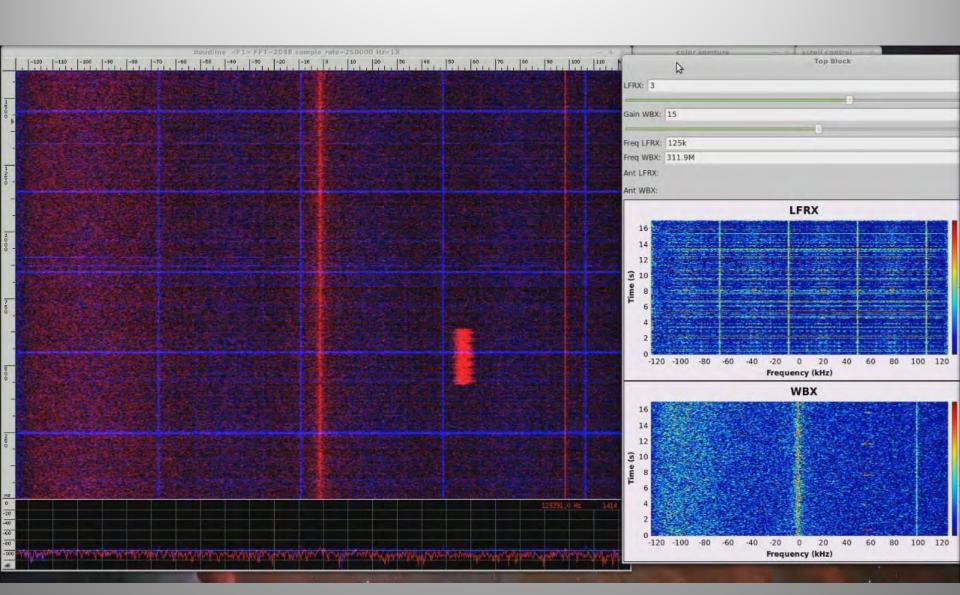


Time-domain Amplitude (UHF)



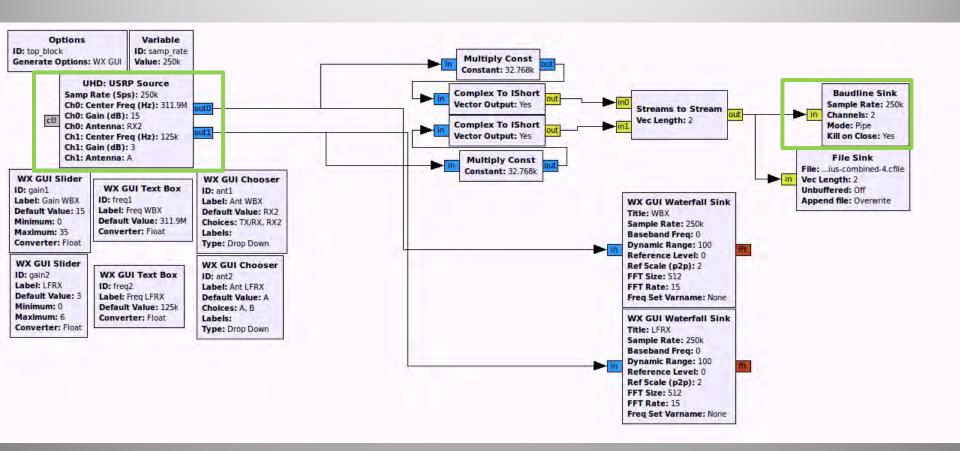


Dual Channel FFT



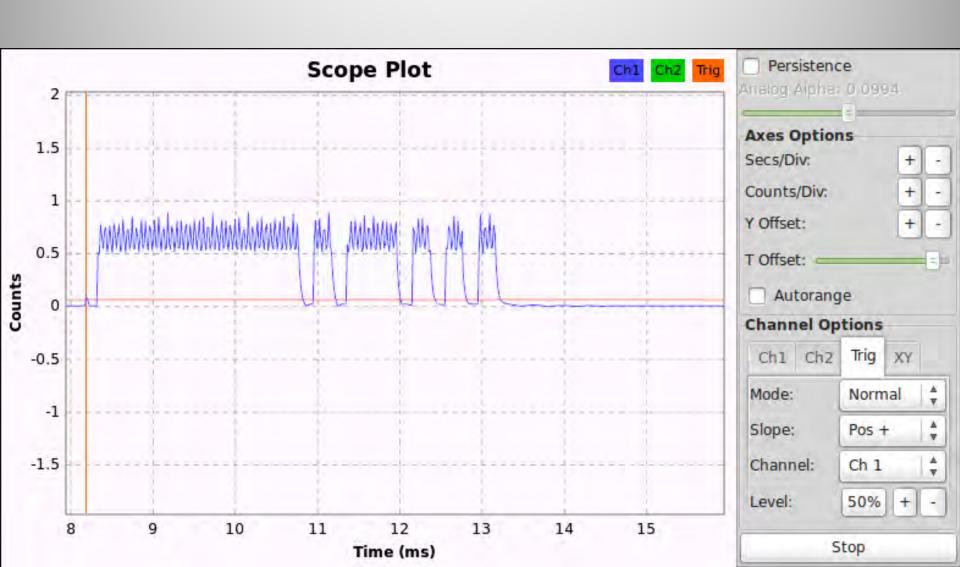


GNU Radio + baudline





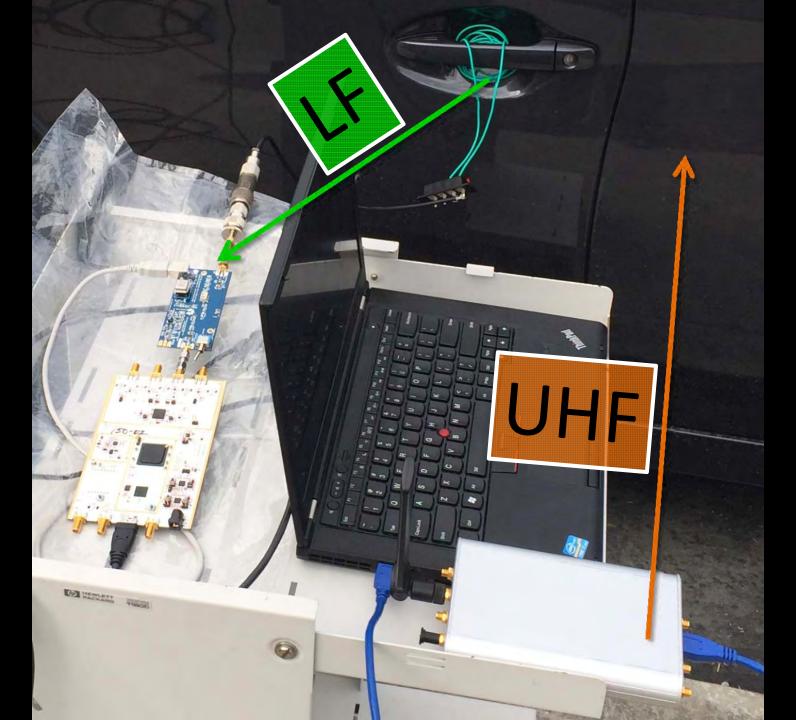
Wake-up

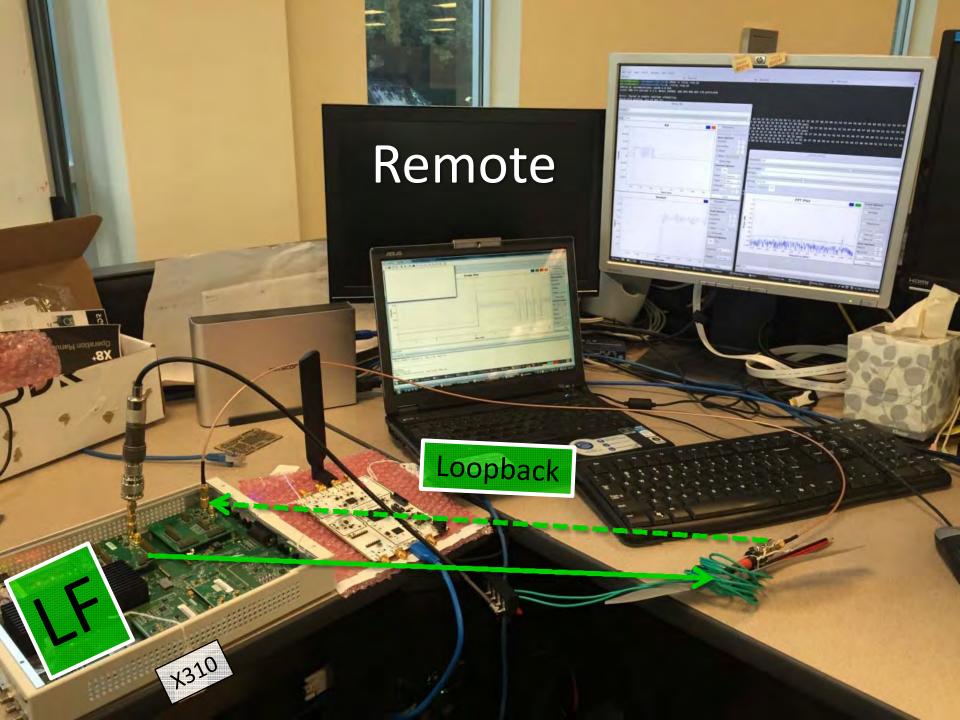


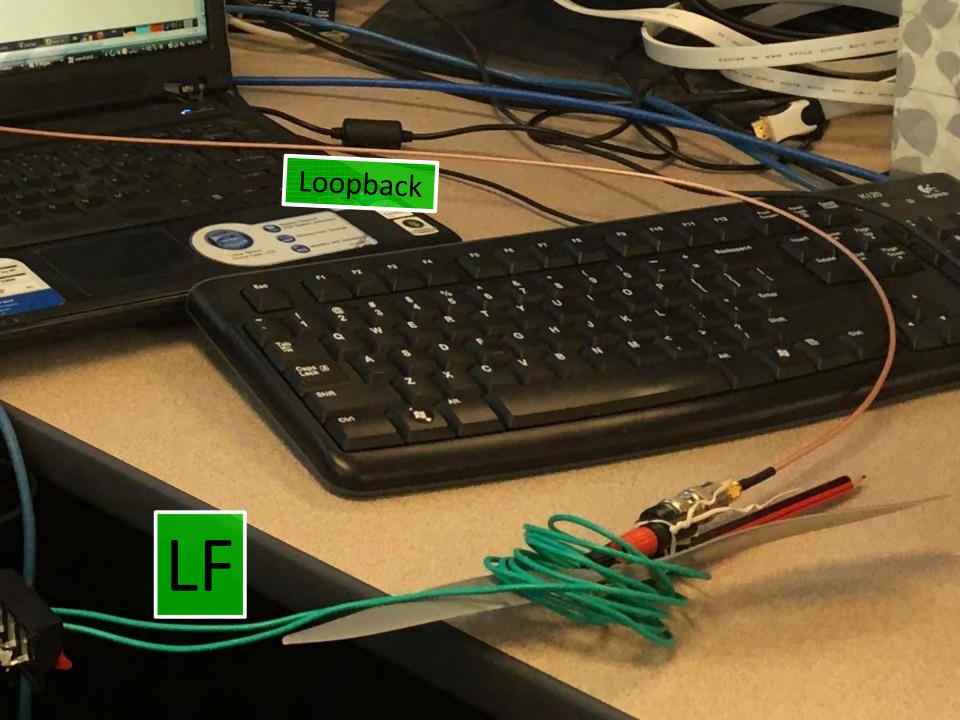
Challenge

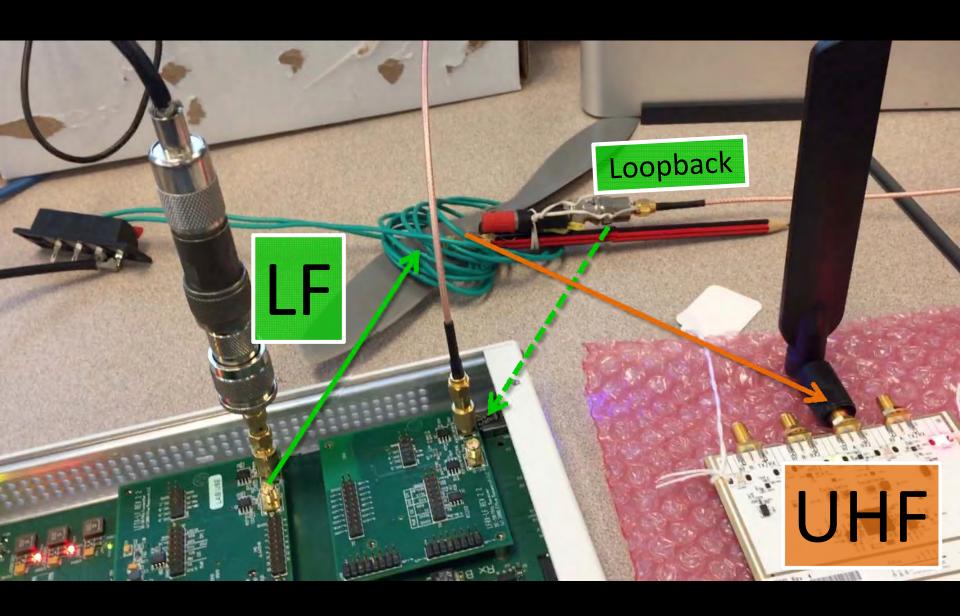


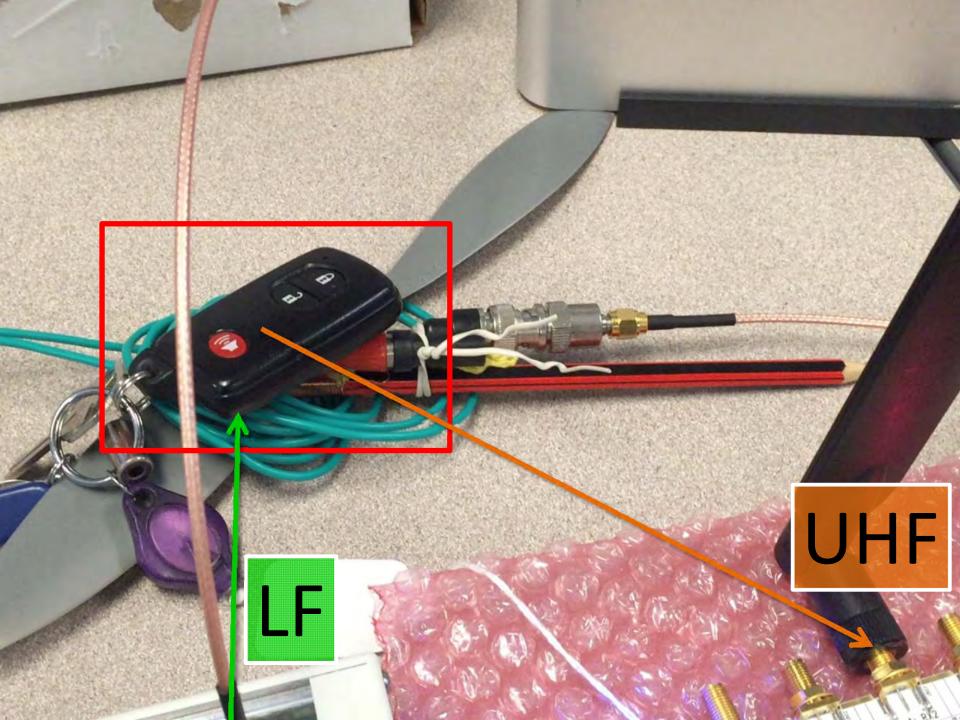


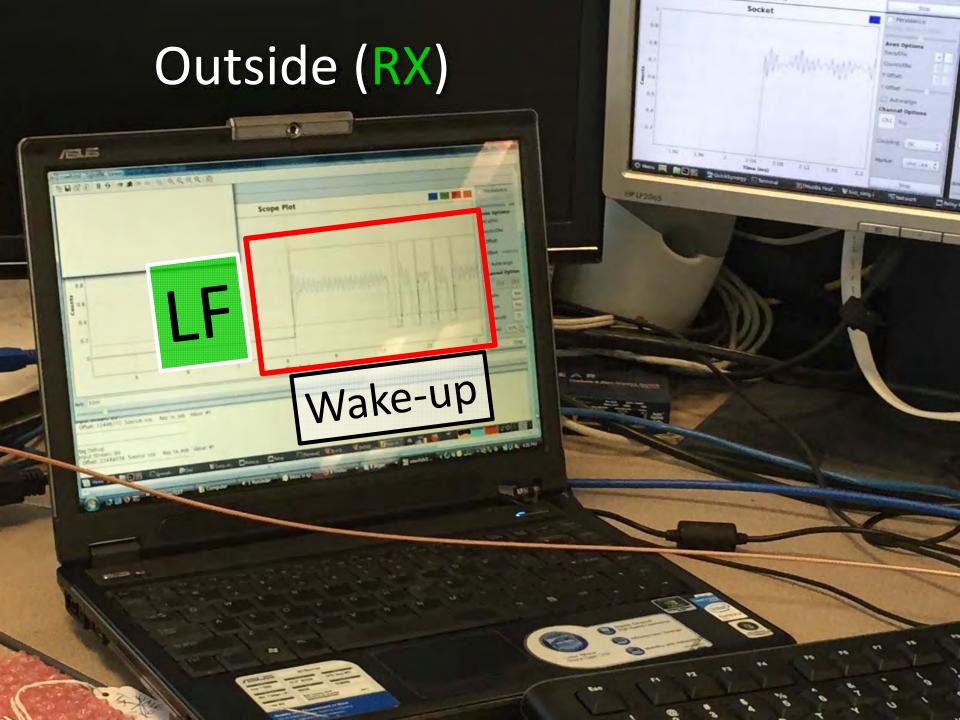




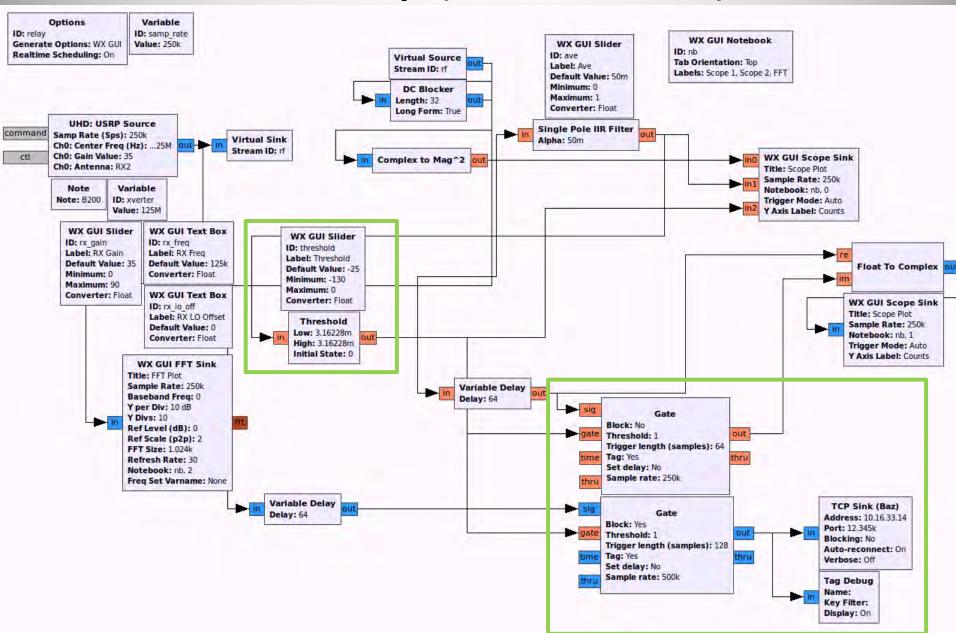






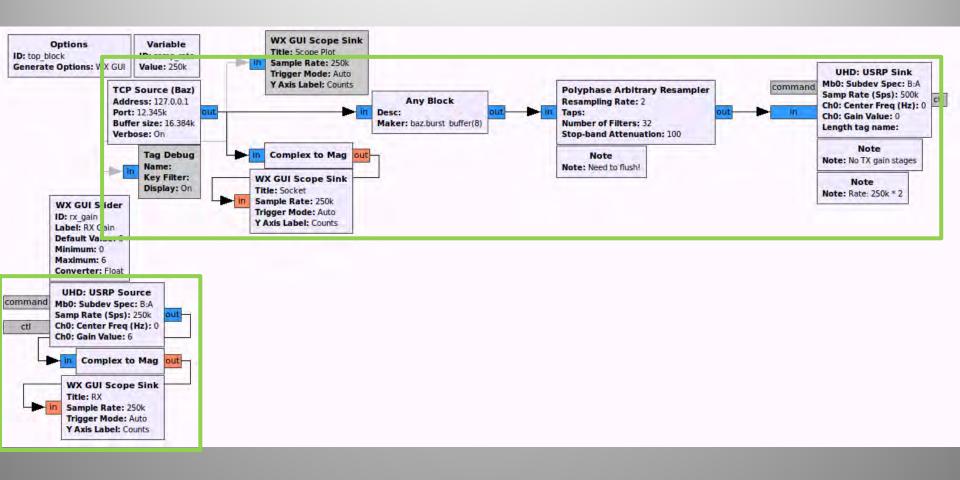


LF Relay (RX Outside)

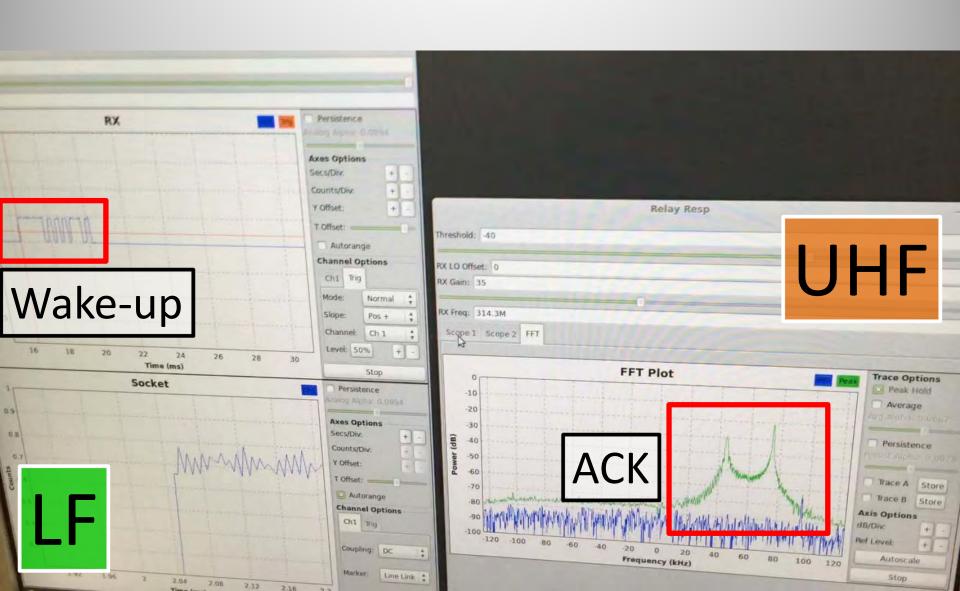




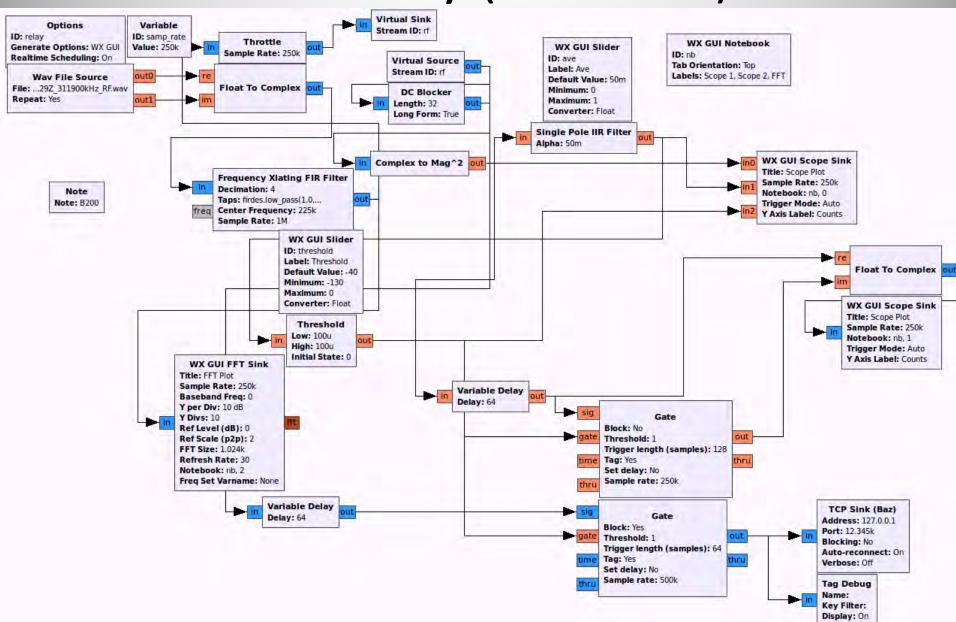
LF Relay (TX Inside)



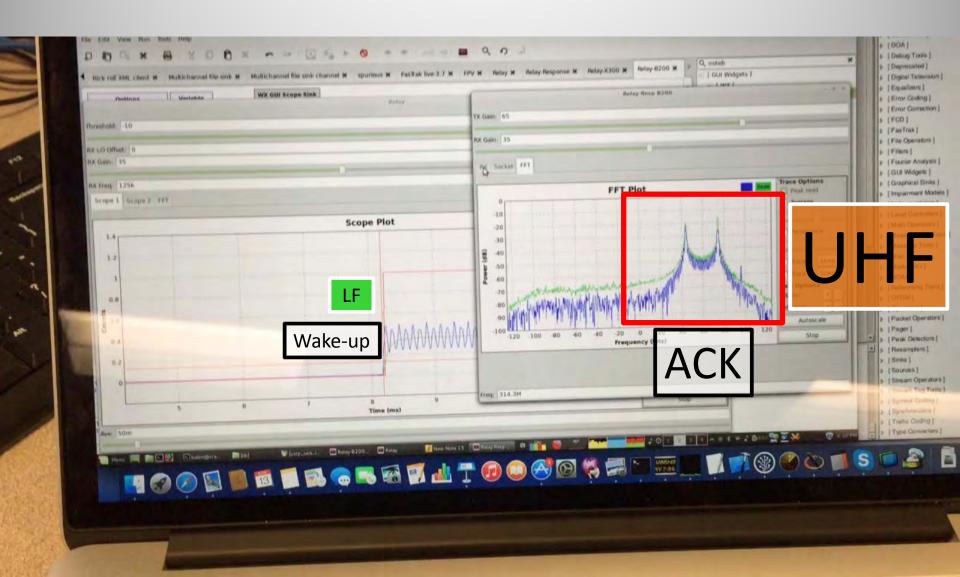
Inside $(TX \rightarrow RX)$



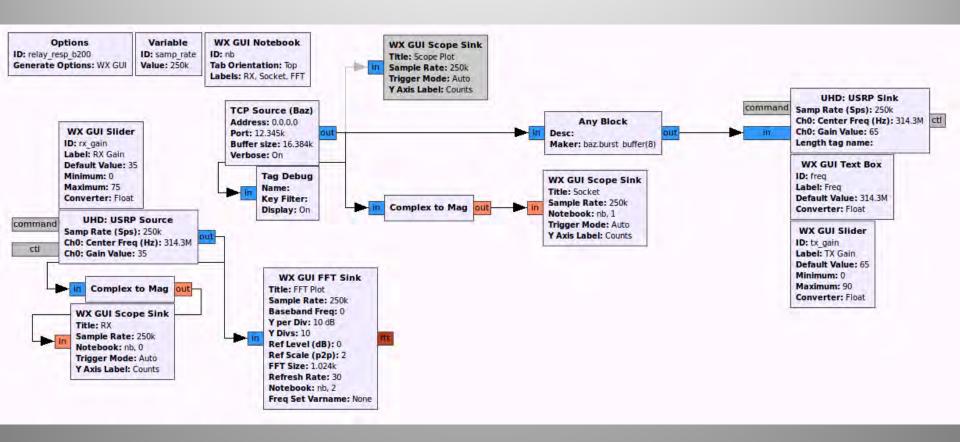
UHF Relay (RX Inside)



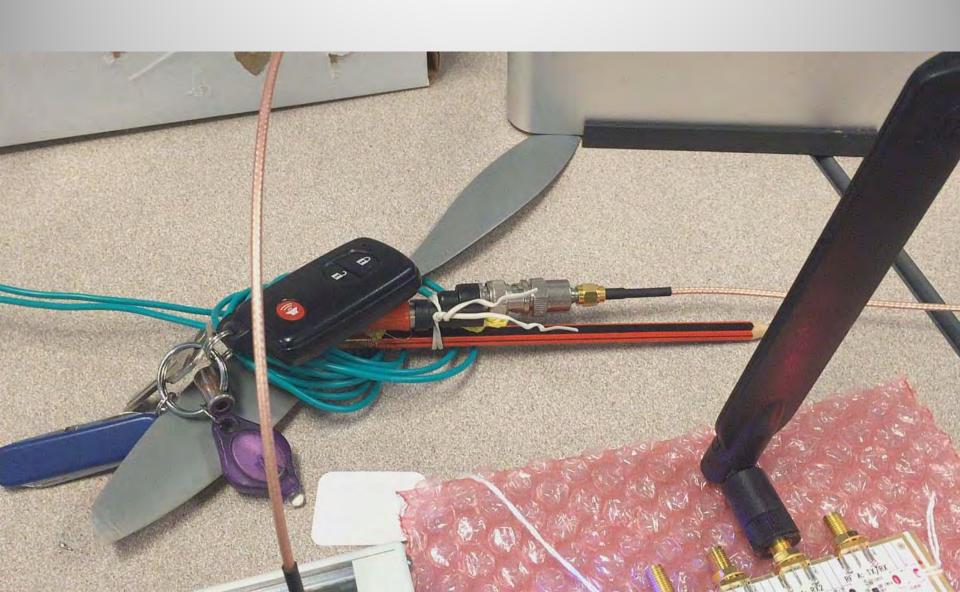
Outside (TX)

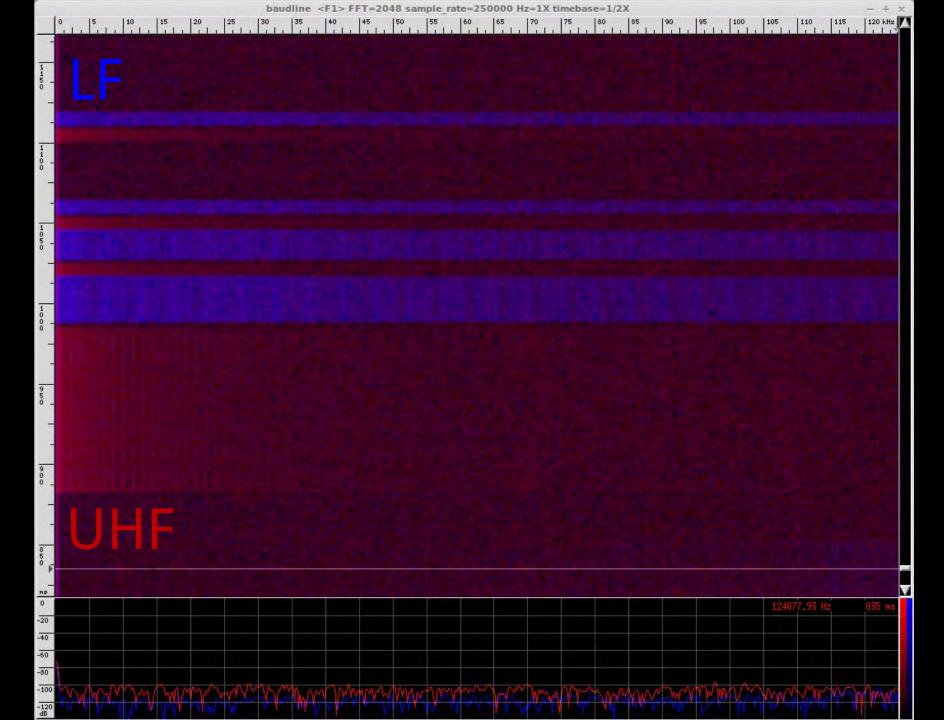


UHF Relay (TX Outside)

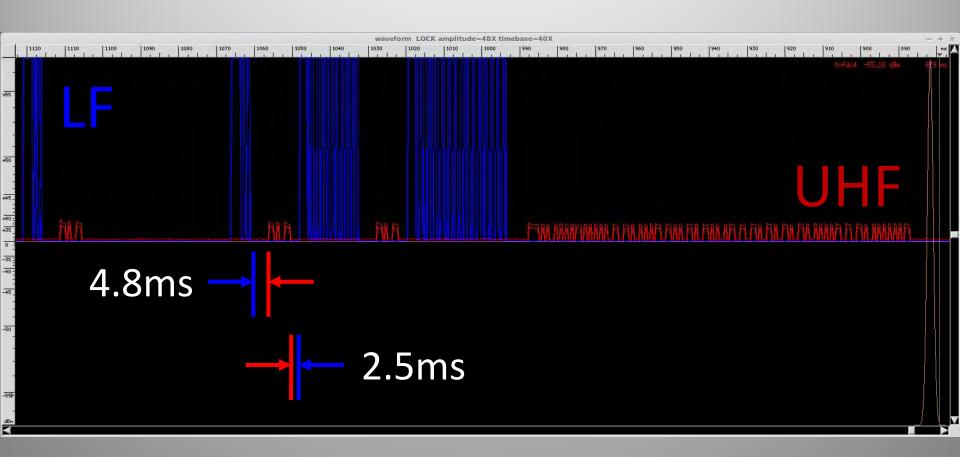


Test





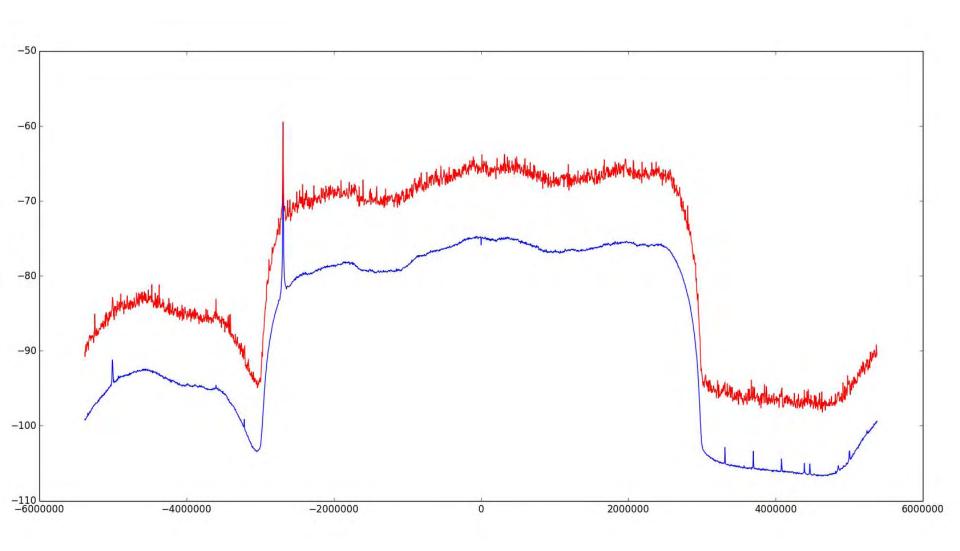
Latency!







ATSC



8VSB

Fundamentals of 8VSB



http://www.tek.com/document/primer/fundamentals-8vsb



8VSB

$$-7 = 000$$

$$-5 = 001$$

$$-3 = 010$$

$$-1 = 011$$

$$+1 = 100$$

$$+3 = 101$$

$$+5 = 110$$

$$+7 = 111$$

8VSB Symbol values before pilot insertion

Calculation of Symbol Rate:

 $Sr (MHz) = 4.5 / 286 \times 684 = 10.76 MHz$

Frequency of a Data Segment:

 $f_{seq} = Sr / 832 = 12.94 \times 10^3 data segments/s$

Data Frame Rate:

$$f_{frame} = f_{seg} / 620 = 20.66$$
 frames/s

Total Number of Bits:

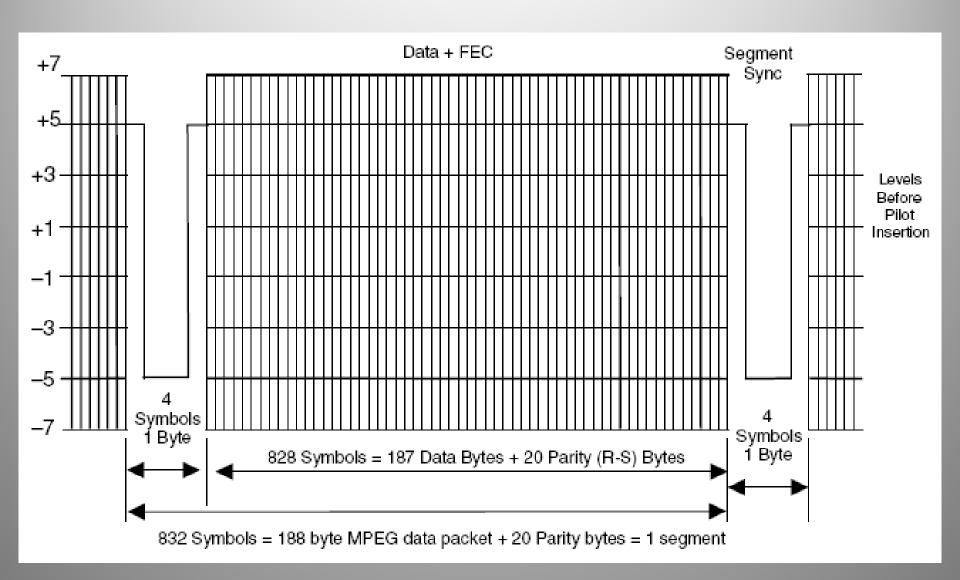
187 data + 20 RS = 207 byte packet = 1656 bits

Trellis coding requires:

 $3/2 \times 1656$ bits = 2484 bits

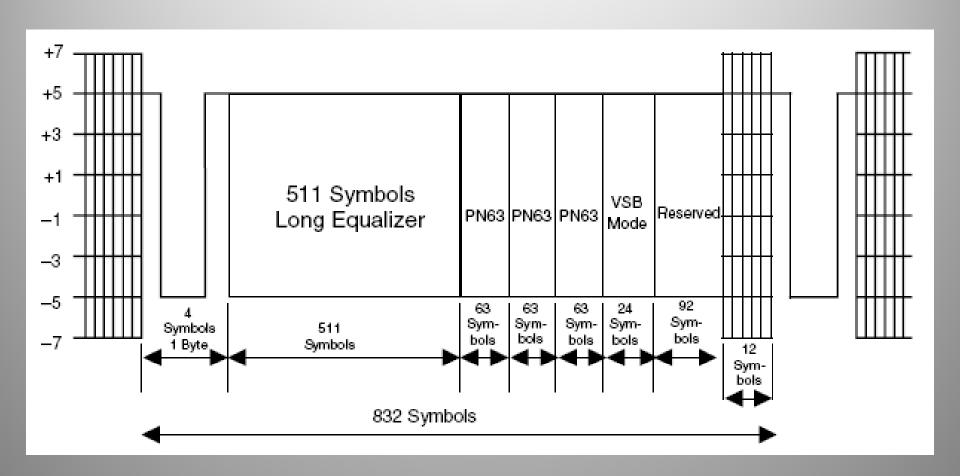


Synchronisation



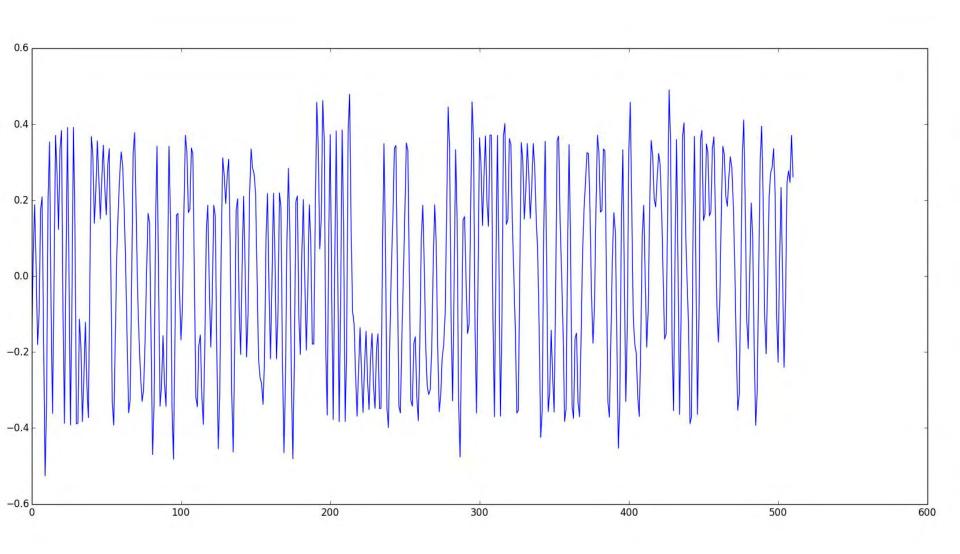


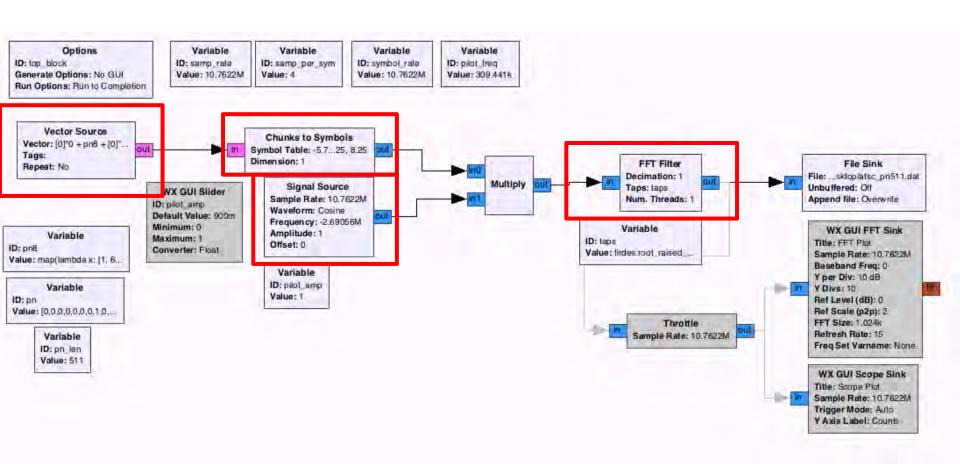
Synchronisation





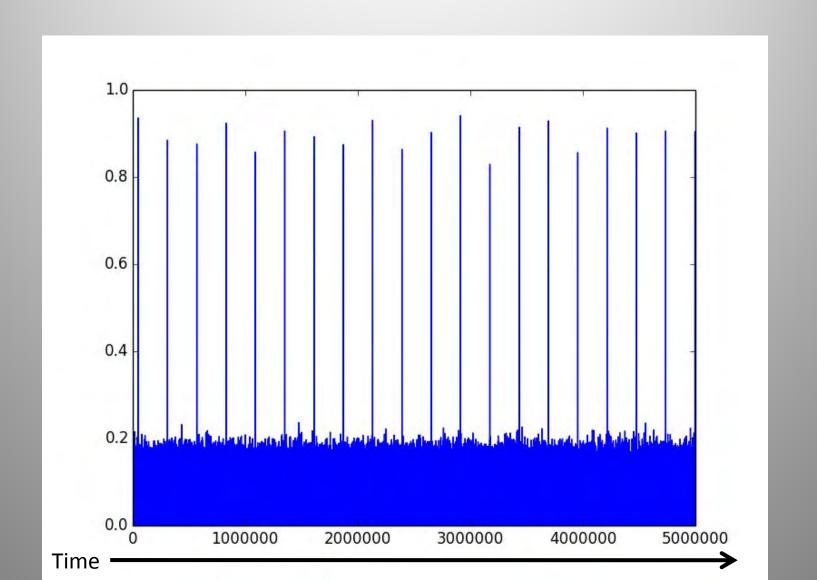
PN511



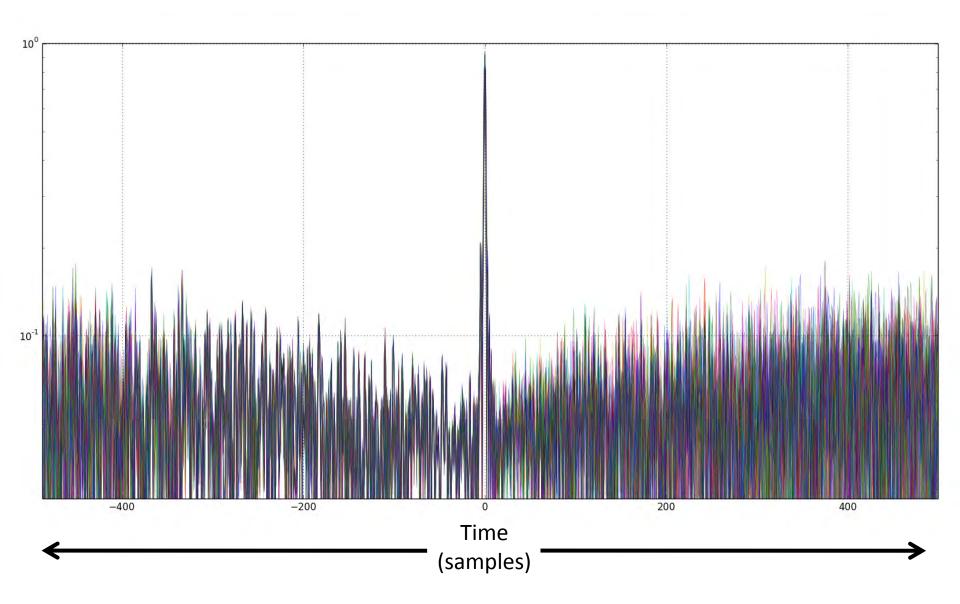




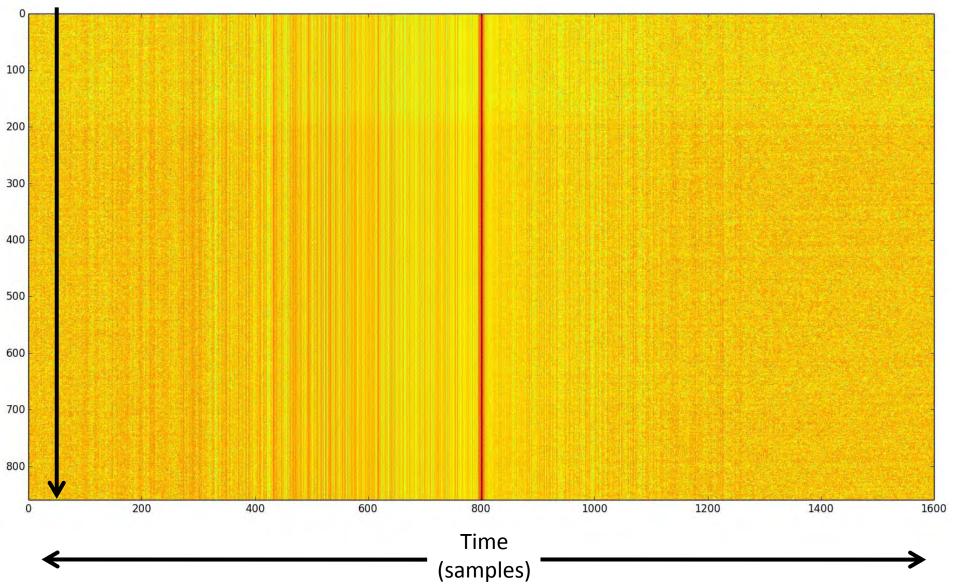
Correlation Peaks







Time (between correlation peaks)

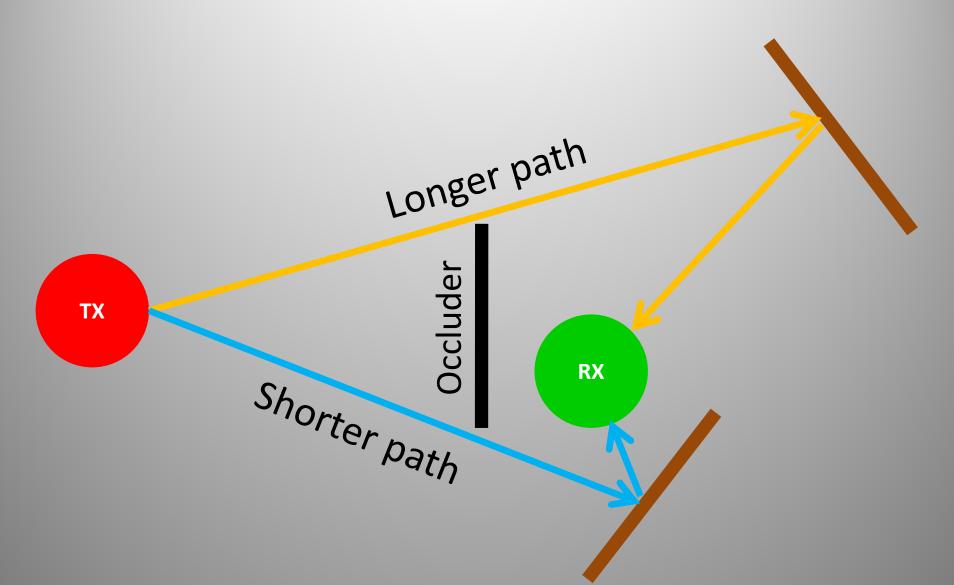


Direct Path

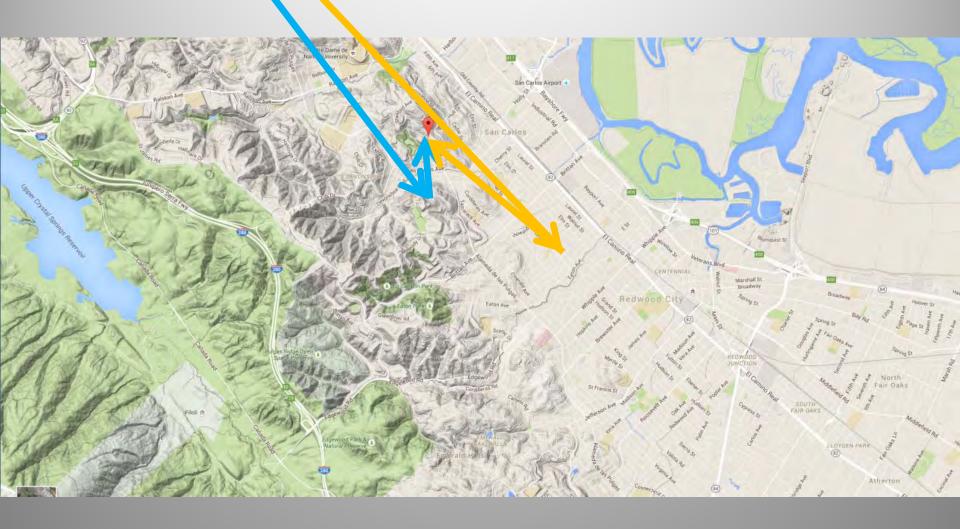
Longer path

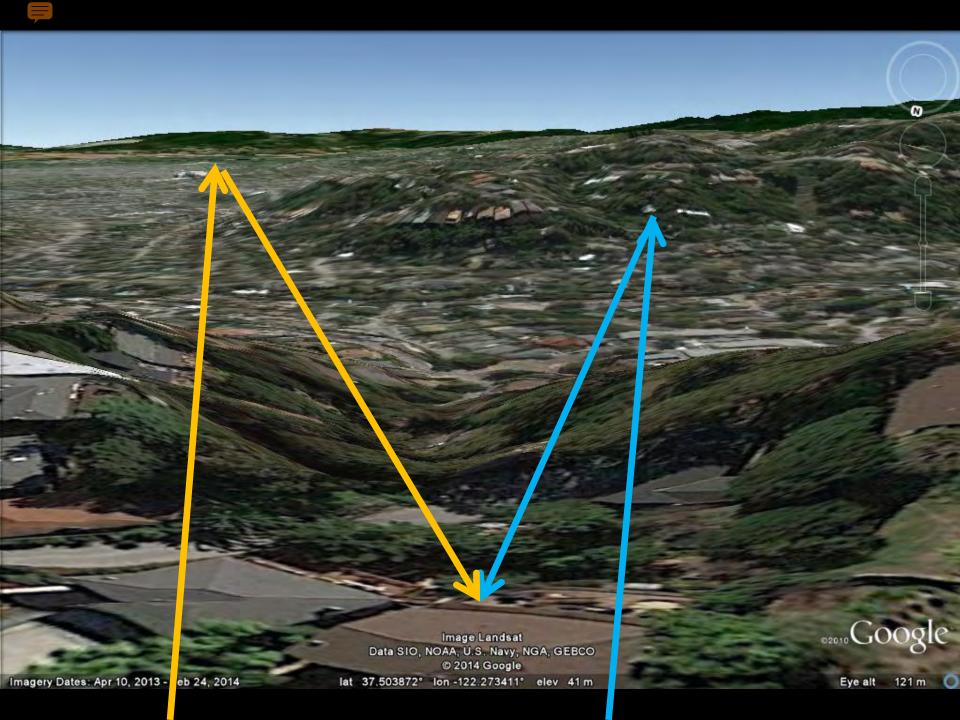
No reflection RX

Multipath

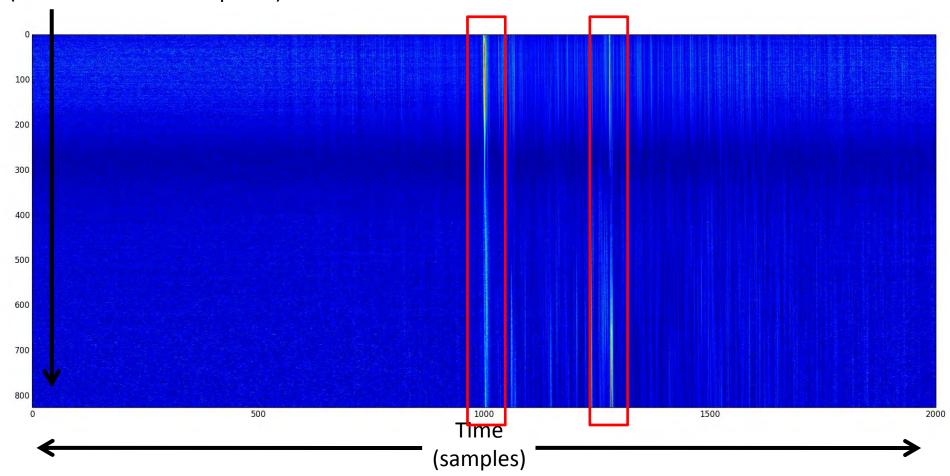


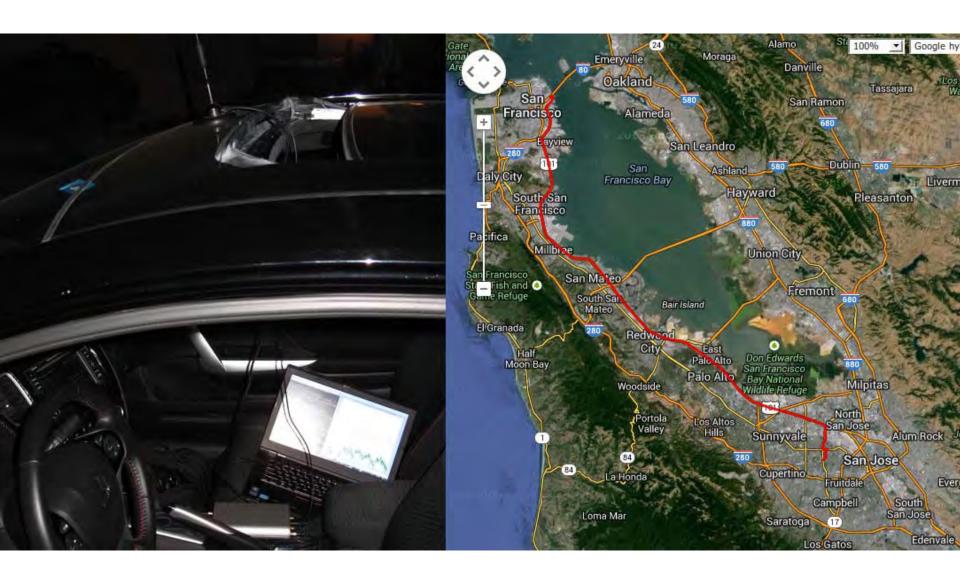
Map



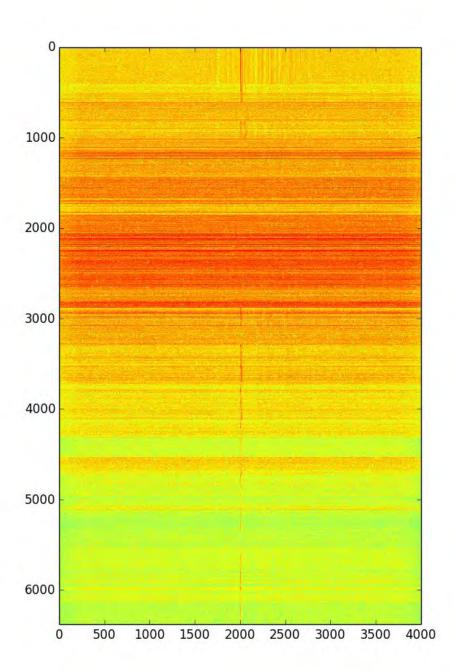


Time (between correlation peaks)

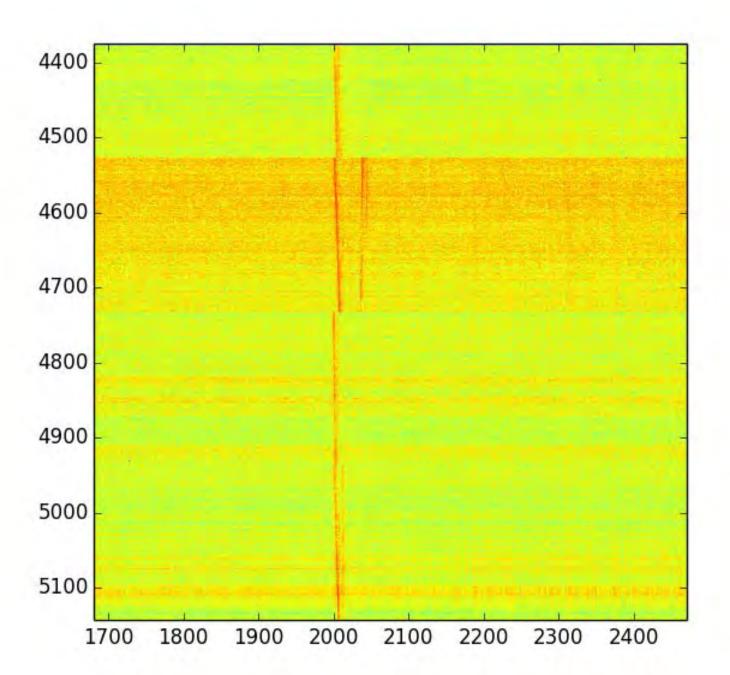




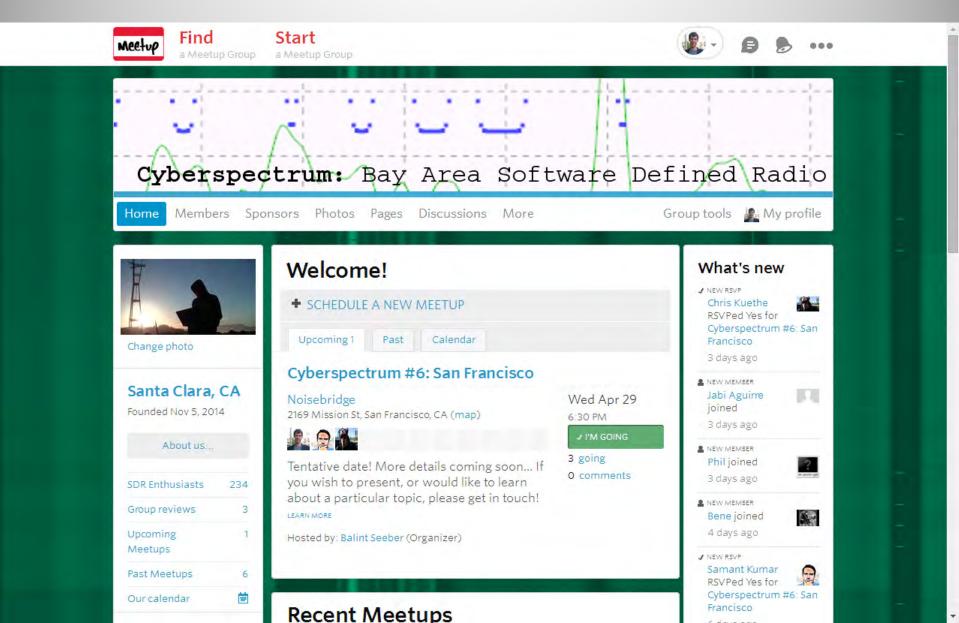








Cyberspectrum SDR Meetups



Cyberspectrum #10 Washington, D.C.

meetup.com/Cyberspectrum



Ted and Karyn

Hume Center for National Security and Technology

Wednesday 26th

