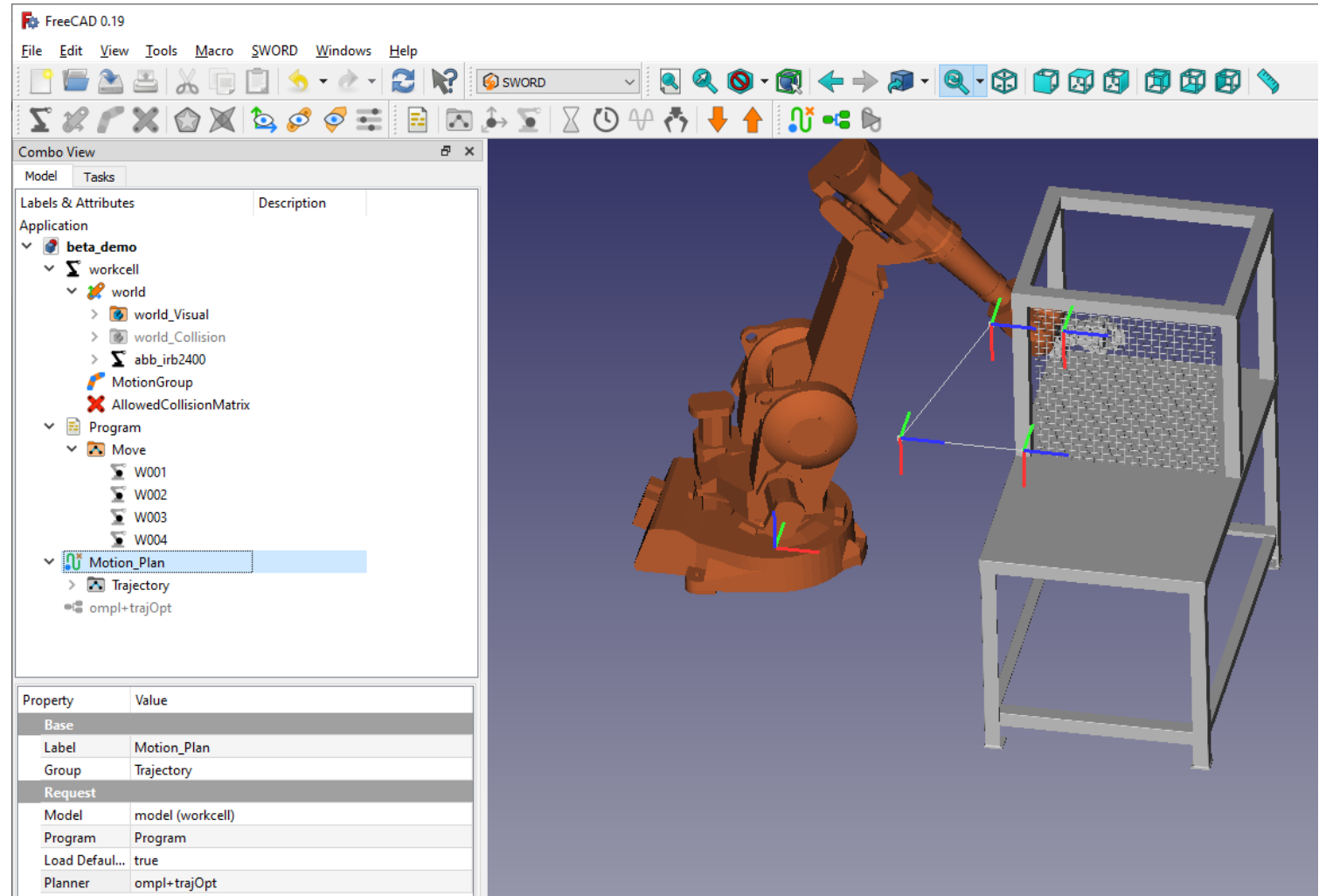# SwRI Workbench for Offline Robotic Development

- FreeCAD-based

- Targeted at **both**:
  - Software Developers
  - Robotics Engineers

- Based on ROS / Tesseract Toolsets

SwRI Workbench for Offline Robotic Development

Current Capabilities:
- URDF Editor
- Motion Waypoints (manual)
- Multiple Motion Planners
  - OMPL, Descartes, TrajOpt
- Custom Planning Pipeline

Beta-Testing Release
Planned for **THIS WEEK**

Contact Matt if interested