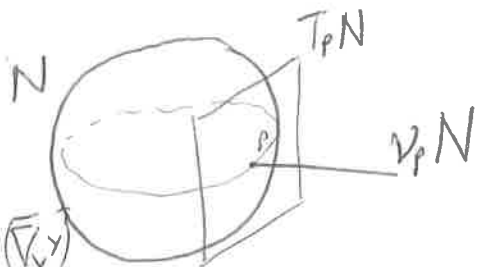


THE SECOND FUNDAMENTAL FORM.

Last time: $N \rightarrow M$ isometric immersion. $T_p M = T_p N \oplus \nu_p N$

$X, Y \in \mathcal{X}(N) \mapsto \bar{\nabla}_X Y \in \mathcal{X}(M)|_N$, i.e.

$$\forall p \in N, (\bar{\nabla}_X Y)_p \in T_p M$$



$$(\bar{\nabla}_X Y)_p^T = (\nabla_X Y)_p \quad \text{connection} \quad (\bar{\nabla}_X Y)^T = f \cdot (\bar{\nabla}_X Y) + X(p) \cdot Y$$

$$(\bar{\nabla}_X Y)_p^\perp = \text{II}(X, Y) \quad \text{tensor} \quad (\bar{\nabla}_X Y)^\perp = f \cdot (\bar{\nabla}_X Y)^\perp$$

$$\text{II}''(X, fY) = f \cdot \text{II}(X, Y)$$

$\gamma: I \rightarrow N$ curve $\nabla_{\gamma'} \gamma'$ acceleration of γ

γ geodesic $\Leftrightarrow \nabla_{\gamma'} \gamma' = 0$ no acceleration (no forces act upon γ)

Supp. $\gamma: I \rightarrow N$ geodesic, $\gamma: I \rightarrow N \rightarrow M$



$$\Rightarrow \bar{\nabla}_{\gamma'} \gamma' = (\nabla_{\gamma'} \gamma')^T + (\nabla_{\gamma'} \gamma')^\perp = \nabla_{\gamma'} \gamma' + \text{II}(\gamma', \gamma')$$

$\Rightarrow \text{II}(\gamma', \gamma')$ measures the obstruction of γ from being a geod. in M as well.

PROP: $\varphi: N \hookrightarrow M$ isometric immersion. Then the geods in N are geods of

M iff. $\text{II} \equiv 0$

Pf. if $\text{II} = 0 \Rightarrow \forall \gamma: I \rightarrow N$ geodesic, $\bar{\nabla}_{\gamma'} \gamma' = \overset{\gamma \text{ geod } 0}{\nabla_{\gamma'} \gamma'} + \overset{0}{\text{II}(\gamma', \gamma')} = 0$

$\Rightarrow \gamma$ is a geod in M .

Suppose every geod. of N is a geodesic of M as well. $\forall v \in T_p N$, let

$\gamma: I \rightarrow N$ geod. st. $\gamma'(0) = v$ then

$$0 = \bar{\nabla}_{\gamma'} \gamma' = \nabla_{\gamma'} \gamma' + \text{II}(v, v) = \text{II}(v, v) \Rightarrow \text{II}(v, v) = 0 \quad \forall v \in T_p N.$$

$$\forall v, w \in T_p N \quad 0 = \text{II}(v+w, v+w) = \text{II}(v, v) + \text{II}(w, w) + \text{II}(v, w) + \text{II}(w, v)$$

$$= 2 \text{II}(v, w) \Rightarrow \text{II}(v, w) = 0 \quad \forall v, w \in T_p N. \quad \square$$

Def: If N satisfies conditions of proposition, it is called **TOTALLY GEODESIC**.

Ex: - $\gamma: \mathbb{R} \rightarrow M$ geodesic is a Totally geodesic immersion.

- $M = \mathbb{R}^m, \mathbb{R}^n \hookrightarrow \mathbb{R}^m$ affine subspace is totally geodesic.
 $v \mapsto A \cdot v + b$

- $(M_1 \times M_2, g_1 \times g_2)$ product mfd. $\forall q \in M_2,$
 $M_1 \rightarrow M_1 \times \{q\} \subseteq M_1 \times M_2$ is an isometric immersion.
 $p \mapsto (p, q)$

PROP: $N \rightarrow M$ totally geodesic immersion. Then $\forall p \in N, \exists U$
 $\exists U \ni p$ nbd in N , st.

$$\forall q_1, q_2 \in U, d_N(q_1, q_2) = d_M(q_1, q_2).$$

Pf: Take ϵ small enough, that $B_\epsilon^M(p) = \exp_p(B_\epsilon(0) \subseteq T_p M)$ are strongly convex
 and $B_\epsilon^N(p) = \exp_p(B_\epsilon(0) \subseteq T_p N)$ are strongly convex

Notice $B_\epsilon^N(p) \hookrightarrow B_\epsilon^M(p)$. Take $q_1, q_2 \in B_\epsilon^N(p) =: U$

Then: $B_\epsilon^N(p)$ strongly convex $\Rightarrow \exists!$ (min) geodesic γ in $B_\epsilon^N(p)$ $q_1 \rightsquigarrow q_2$
 $B_\epsilon^M(p)$ strongly convex $\Rightarrow \exists!$ (min) geodesic $\bar{\gamma}$ in $B_\epsilon^M(p)$ $q_1 \rightsquigarrow q_2$

N Totally geodesic + $B_\epsilon^N(p) \hookrightarrow B_\epsilon^M(p) \Rightarrow \gamma$ is a geodesic in B_ϵ^M $q_1 \rightsquigarrow q_2$
 $\Rightarrow \gamma = \bar{\gamma} \Rightarrow$ ~~st~~

$$\Rightarrow d_N(q_1, q_2) = l(\gamma) = l(\bar{\gamma}) = d_M(q_1, q_2)$$

Rmk: not global in general!



N geod of $M \Rightarrow N$ totally geodesic.
 $d_N(p, q) > d_M(p, q)$

Stronger conditions: $N \rightarrow M$ (complete mfd)

1. Convex if $\forall p, q \in N, \exists M$ -minimizing geod. $p \rightsquigarrow q$ in N

2. Totally convex if $\forall p, q \in N, \forall \gamma$ M -geod. $p \rightsquigarrow q, \gamma \cap N = \{p, q\}$

Ex:



Tot. geod.

✓

✓

✓

convex

✗

✓

✓

Tot. convex

✗

✗

✓

RMK: If $N \hookrightarrow M$ convex, then $\forall p, q \in N, d_N(p, q) = d_M(p, q)$

Def: $N \rightarrow M, p \in N \Rightarrow$ def: mean curvature operator

$$K_p: \mathfrak{v}_p N \rightarrow \mathbb{R}$$

$$\eta \mapsto \text{tr } S_\eta = \sum_i \langle S_\eta e_i, e_i \rangle = \langle \eta, \sum_i \mathbb{I}(e_i, e_i) \rangle \quad e_i \text{ onb of } T_p N$$

Def: mean curvature vector

$$H_p \in \mathfrak{v}_p N \text{ st. } \forall \eta \in \mathfrak{v}_p N, K_p(\eta) = \langle \eta, H_p \rangle$$

\Downarrow

$$H_p = \sum_i \mathbb{I}(e_i, e_i) \quad e_i \text{ onb of } T_p N$$

Def: mean curvature vector field $H \in \Gamma(\mathfrak{v}N)$

$$H: N \rightarrow \mathfrak{v}N, p \mapsto H_p$$

Fact: H points in the direction of maximal decrease of area.



Def: $N \subseteq M$ is called Minimal if $H \equiv 0$

N minimal is a "critical point for the area"

