MANUALS



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MGV34RANGE

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REV:14_03_2021



Thank you for choosing a Montanari product.

Since 1970, Montanari Group has been focused on providing its customers with the best traction machines and components for lifts and escalators.

We are proud to have you as a customer and user of the Montanari traction machines, and we are confident that we can work together for a long time.

Thanks again for your choice.

Massimo Montanari CEO of Montanari Group



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14	03/03/2021	Update	Marketing Dept	Technical Dept - Alberto Mantovani	STEFANO BERTONI (DTE)

WARNING SYMBOLS USED IN THE MANUAL:

	It indicates that safety measures must be taken to avoid electric shock.
	It indicates that safety measures must be taken to prevent personal injury.
\bigwedge	It indicates that safety measures must be taken to prevent damage to components.
<u></u>	It indicates that safety measures must be taken to prevent burns due to contact with hot/ overheated surface.
TIP	It indicates useful information before and during the installation step.
	It refers to specific parts of the manual.
4	It refers to the proper product disposal.

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### 1. GENERAL INFORMATION

### 1.1 Introduction

These operating instructions must always be available for consultation. No liability is accepted for any malfunction due to installation not conforming to specifications, except in cases approved by Montanari Giulio & C.

All persons involved in the installation, operation, maintenance and repair of the unit must have read and understood the instructions.

No liability is accepted for damage, breakage or accident caused by failure to follow the instructions.

To make technical improvements, Montanari reserves the right, if deemed necessary, to modify the units and accessories, preserving their essential characteristics and improving efficiency and safety, without notice.

### 1.2 Copyright

All rights to these operating instructions belong to Montanari Giulio & C. S.r.l. The information in this manual may not be reproduced or used in an unauthorized manner or made available to third parties without prior approval.

If you have any questions, please contact:

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2. SAFETY

2.1 Intended use

The MGV34 gearless machine is supplied ready for safe and reliable use. Any modification by the user that may affect safety or reliability is prohibited; it is also prohibited to tamper with devices or functions designed to prevent accidental contact.

### It can be used in systems with and without machine room (MR - MRL).



The Montanari MGV34 gearless machine must be used and operated in strict compliance with the conditions set out in the supply contract.

Technical specifications considered: speed, cab capacity, cab weight, presence or absence of compensation, roping at the time of order.

No liability is accepted for any malfunction due to installation not conforming to specifications, except in cases approved by Montanari Giulio & C..

### 2.2 User's obligations

The operator must ensure that all persons involved in installation, operation, maintenance and repair have read and understood the supplied operating instructions and have adapted to them in order to:

- Avoid damage to property or persons.
- Ensure safe and reliable operation of the unit.
- Avoid breakage and environmental damage due to misuse.

In particular:

• Always observe the relevant environmental and safety regulations when transporting, assembling, installing, operating, maintaining and dismantling the unit.

• The unit must only be used, maintained and repaired by authorized, properly trained and qualified personnel.

- The gearbox must not be cleaned using high-pressure cleaning equipment.
- All work must be carried out with care and with due attention to safety.
- Any work on the unit should only be carried out when it is not in operation.

• A warning must be placed on the main switch to clearly indicate that work is in progress on the unit.

- No welding must be carried out on the unit.
- Do not use the unit as a grounding point for welding operations.

• If any changes are detected (e.g. overheating or unusual noise) during operation, switch off immediately.

• Rotating components must be equipped with appropriate guards to prevent contact.

• If the unit is intended for installation in plant or machinery, the manufacturer of such plant or machinery must ensure that the standards, indications and descriptions contained in these operating instructions are incorporated into its own instructions.

• The information on the warning or identification plates must be complied with. These plates must be kept clean and legible at all times. Missing plates must be replaced.

- All spare parts can be obtained from Montanari Group.
- 2.3 Correct disposal

Respect the environment and dispose of the product according to the regulations in force in the country of installation.

### Specific hazards 2.4

Depending on the conditions of use, the surface of the unit can become very hoť.



### 2.5 Legal References

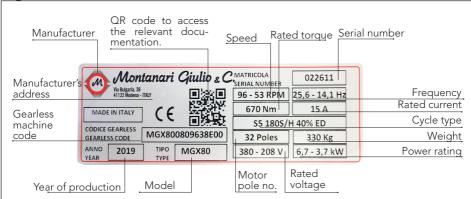
Tab. 1 Ν Description Norm 1 UNI 10147 Maintenance: Terminology. Safety rules for the construction and installation of lifts - Lifts for the transport of persons 2 FN 81-20 and goods. 3 FN 81-50 Safety rules for the construction and installation of lifts - Examinations and tests. Safety rules for the construction and installation of lifts - Lifts for the transport of persons EN 81-21 4 and goods - Part 21: New passenger and goods passenger lifts in existing building.

3 **IDENTIFICATION AND DATA** 

### 3.1 Identification plate

The data on the plate are:

### Fig. 1



GEARLESS MACHINE TECHNICAL CHARACTERISTICS: MGV34S	TECHNIC	2	۲, I	CHA	RA	CTER	STIC	S: Mo	GV34S		ĺ				F	Tab. 2
Type Pn <i>Speed Vn</i>	Speed	Nη		Cn	Ч	In Cmax Imax	lmax	EMF	Poles	F	Rs	LS	Static Load	1	Duty Cycle	Weight
kw [RPM] [V]	Σ			[Nm]	$[\forall]$	[Nm]	[A]	[V·s/ rad]	[_N]	[Hz]	[IJ]	[Hm]	[Kg]	[kg·m2]		[Kg]
MGV34151203CJ00 MGV34S 4,3 48 210	210			850	28	1400	50	17	16	6,4	-	15,8	5000	1,35	180S/H 40%	472
MGV34S 8,5 96 210 8	210		8	850	43	1400	73	11	16	12,8	0,46	7,3	5000	1,35	180S/H 40%	472
MGV34153003CJ00 MGV34S 14,2 160 210 85	210	_	8	850	58	1400	102	80	16	21,3	0,25	4	5000	1,35	180S/H 40%	472
MGV34152392CJ00 MGV34S 22,5 239 210 850	210		85	0	81	1400	140	6	16	31,9	0,13	2	5000	1,35	180S/H 40%	472
MGV34150603CJ00 MGV34S 5,3 60 360 85	360		8	850	17,5	1400	32	27	16	80	2,5	39	5000	1,35	180S/H 40%	472
MGV34150963CJ00 MGV34S 8,5 96 360 85	360		õ	850	24	1400	43	20	16	12,8	1,4	22	5000	1,35	180S/H 40%	472
MGV34S 10,7 120 360 85	360		8	850	28	1400	50	17	16	16	-	15,8	5000	1,35	180S/H 40%	472
MGV34152103CJ00 MGV34S 18,7 210 360 85	360		8	850	43	1400	73	11	16	28	0,46	7,3	5000	1,35	180S/H 40%	472
MGV34153003CJ00 MGV34S 26,7 300 360 8	360		ōÓ	850	58	1400	102	∞	16	40	0,25	4	5000	1,35	180S/H 40%	472

# GEARI ESS MACHINE TECHNICAL CHARACTERISTICS: MGV34M

Tab. 3

	MACH		I ECHINICAL CHARACI ERISTICS: MGV34M		בֿ כ	AKA			NI IN	142 J							au. J
MGV34M	Type	Pn	Speed	Nη	C	Ч	Cmax Imax	Imax	EMF	Poles	F	Rs	LS [	Static Load	~	Duty Cycle	Weight
Code machine		kW	[RPM]	$\geq$	[Nm]	$[\forall]$	[Nm]	$[\forall]$	[V·s/ rad]	[_N]	[Hz]	[U]	[mH]	[Kg]	[kg·m2]		[Kg]
MGV34201803CO13 MGV	MGV34M	8,8	80	210	1050	43	1850	81	13	16	10,7	0,44	7,5	5000	2,4	180S/H 40%	539
MGV34202393CO13 MGV34M	MGV34M	13,2	120	210	1050	57	1850	105	10	16	16	0,275	4,4	5000	2,4	180S/H 40%	539
MGV34203803CO13 MGV34M	MGV34M	19,8	180	210	1050	85	1850	150	7	16	24	0,125	2,1	5000	2,4	180S/H 40%	539
MGV34202402CO13 MGV:	MGV34M	26,4	240	210	1050	107	1850	204	5	16	32	0,08	1,3	5000	2,4	180S/H 40%	539
MGV34200483CO13 MGV34M	MGV34M	5,3	48	360	1050	18,5	1850	34	32	16	6,4	2,5	42	5000	2,4	180S/H 40%	539
MGV34200753CO13 MGV34M	MGV34M	8,3	75	360	1050	21	1850	43	26	16	10	1,6	26,5	5000	2,4	180S/H 40%	539
MGV34201203CO13 MGV	MGV34M	13,2	120	360	1050	30,5	1850	57	19	16	16	0,88	15	5000	2,4	180S/H 40%	539
MGV34201803CO13 MGV	MGV34M	19,8	180	360	1050	43	1850	81	13	16	24	0,44	7,5	5000	2,4	180S/H 40%	539
MGV34202393CO13 MGV34M	MGV34M	26,3	239	360	1050	57	1850	105	10	16	31,9	0,275	4,4	5000	2,4	180S/H 40%	539
MGV34203003CO13 MGV34M	MGV34M	33	300	360	1050	69	1850	120	80	16	40	0,19	3,2	5000	2,4	180S/H 40%	539
MGV34203803CO13 MGV	MGV34M	41,8	380	360	1050	85	1850	150	7	16	50,7	0,125	2,1	5000	2,4	180S/H 40%	539

CHINE TECHNICAL CHARACTERISTICS: MGV34ML Tab. 4	- Poles F Rs Ls Static / Duty Weight Load / Cycle Weight	[N°] [Hz] [Ω] [mH] [Kg] [kg·m2] [Kg]	16 6,4 0,54 10 6500 2,7 180S/H 40% 623	16 12,8 0,25 4,6 6500 2,7 180S/H 40% 623	16 16 0,17 3 6500 2,7 1805/H 40% 623	16 21,3 0,1 1,9 6500 2,7 180S/H 40% 623	16 32 0,054 0,96 6500 2,7 180S/H 40% 623	16 8 1,56 28 6500 2,7 180S/H 40% 623	16 12,8 0,69 12 6500 2,7 180S/H 40% 623	16 16 0,54 10 6500 2,7 1805/H 40% 623	16 25,6 0,25 4,6 6500 2,7 180S/H 40% 623	16 31,9 0,17 3 6500 2,7 1805/H 40% 623	16 44 0,1 1,9 6500 2,7 1805/H 40% 623	į	Poles F Rs Ls Static I Duty Weight	[N°] [Hz] [Ω] [mH] [Kg] [kg·m2] [Kg]	16 6,4 0,54 10 6500 2,7 180S/H 40% 677	16 11,3 0,25 4,6 6500 2,7 180S/H 40% 677	16 16 0,17 3 6500 2,7 180S/H 40% 677	16 21,3 0,1 1,9 6500 2,7 1805/H 40% 677	16 30,7 0,054 0,96 6500 2,7 1805/H 40% 677	16 6,4 1,56 28 6500 2,7 180S/H 40% 677	16 12,8 0,69 12 6500 2,7 180S/H 40% 677	16 16 0,54 10 6500 2,7 180S/H 40% 677	16 25,6 0,25 4,6 6500 2,7 180S/H 40% 677	16 31,9 0,17 3 6500 2,7 1805/H 40% 677
	ט <i>א</i>   	.g·m2]	-												/ Cycl	·m2]										
	Static Load		6500	6500	6500	6500	6500	6500	6500	6500	6500	6500	6500	Ctatio	static Load											
	LS _	[Hm]	10	4,6	e	1,9	0,96	28	12	10	4,6	m	1,9	Ī		[HM]	10	4,6	ę	1,9	0,96	28	12	10	4,6	m
	Rs	[U]	0,54	0,25	0,17	0,1	0,054	1,56	0,69	0,54	0,25	0,17	0,1	Ī	Rs	[U]	0,54	0,25	0,17	0,1	0,054	1,56	0,69	0,54	0,25	0,17
٩L		[Hz]	6,4	12,8	16	21,3	32	∞	12,8	16	25,6	31,9	44	,	F	[Hz]	6,4	11,3	16	21,3	30,7	6,4	12,8	16	25,6	31,9
16 \ 34			16	16	16	16	16	16	16	16	16	16	16	5		[N°]	16	16	16	16	16	16	16	16	16	16
≥ 	x EMF	[V·s/ rad]	19	13	;	∞	9	32	21	19	13	1	∞		EMF	[V·s/ rad]	19	13	11	80	9	31	21	19	13	
	k Imax	[\]	70	104	127	168	231	42	61	70	104	127	168		Imax	$[ \forall ]$	86	124	152	196	273	51	77	86	124	152
	Cmax	[Nm]	2400	2400	2400	2400	2400	2400	2400	2400	2400	2400	2400		Cmax Imax	[Mm]	2800	2800	2800	2800	2800	2800	2800	2800	2800	2800
	ЦЛ	Ā	40	28	72	96	136	23,5	36	40	28	72	96		ln l	$[ \forall$	47	68	85	109	157	27,5	42	47	68	85
5	Cn	[Mm]	1400	1400	1400	1400	1400	1400	1400	1400	1400	1400	1400	5	Cn	[Mm]	1620	1620	1620	1620	1620	1620	1620	1620	1620	1620
5	Ŋ	$\geq$	210	210	210	210	210	360	360	360	360	360	360	5	۲'n	$\geq$	210	210	210	210	210	360	360	360	360	340
	Speed	[RPM]	48	96	120	160	240	99	96	120	192	239	330		Speed	[RPM]	48	85	120	160	230	48	96	120	192	239
	Pn	kW	7,03	14,1	17,6	23,5	35,2	8,8	14,1	17,6	28,1	35	48,4		Pn	КХ	8,1	14,4	20,3	27,1	39	8,1	16,3	20,3	32,6	40.5
	Type		MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML	MGV34ML		Type		MGV34L	MGV34L	MGV34L	MGV34L	MGV34L	MGV34L	MGV34L	MGV34L	MGV34L	MGV34
DEARLESS INA	MGV34ML	Code machine	MGV34311203CO11 MGV34ML	MGV34311913CO11 MGV34ML	MGV34312393CO11 MGV34ML	MGV34313303CO11 MGV34ML	MGV34312402CO11 MGV34ML	MGV34310603CO11 MGV34ML	MGV34310963CO11 MGV34ML	MGV34311203CO11 MGV34ML	MGV34311913CO11 MGV34ML	MGV34312393CO11 MGV34ML	MGV34313303CO11 MGV34ML		MGV34L	Code machine	MGV343112036Q12 MGV34L	MGV343119136Q12 MGV34L	MGV343123936Q12 MGV34L	MGV343130036Q12 MGV34L	MGV343123026Q12 MGV34L	MGV343104836Q12 MGV34L	MGV343109636Q12 MGV34L	MGV343112036Q12 MGV34L	MGV343119136Q12 MGV34L	MGV343123936012 MGV34L

MGV34 S - M - ML - L | ENGLISH 🏶



Tab. 6

		BRAK	E CHARACTERISTIC	CS		
Model	Brake model	Power (Pn)	Voltage (Vn)	Current (In)	Force (Cn)	Certificate
		[W]	[V]	[A]	[Nm]	
MGV34S	RTW800	2 x 502 - 2 x 127	207V _{DC PEAK} - 104V _{DC HOLD}	2.4 - 1.2	2 x950	EU-BD 1014
MGV34M	RTW1000	2 x 158	207V _{DC}	2 x 0,76	2 x1200	EU-BD 1014
MGV34ML	RTW1000	2 x 158	207V _{DC}	2 x 0,76	2 x1200	EU-BD 1014
MGV34L	RSR1500	2 x 165	207V _{DC}	2 x 0,80	2 x1700	EU-BD 766

# 3.2 Dimensions

The technical drawing and the overall dimensions follow.

Tab.	7
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		MGV	34S - Fig. 2		
Pul	ley		Ropes		Dimensions
ØD	F	Ø	min max	Pitch	А
mm	mm	mm	n°	mm	mm
240	130	6,5	6 - 10	12	167
320		8	3 - 10	17	
400	180	10	3 - 10	17	150
480		12	3 - 9	20	153
520	145	13	3 - 7	20	

		MGV	34M - Fig. 3	}	
Pul	ley		Ropes		Dimensions
ØD	F	Ø	min max	Pitch	А
mm	mm	mm	n°	mm	mm
320		8	3 - 10	17	
400	180	10	3 - 10	17	153
480		12	3 - 9	20	100
520	145	13	3 - 7	20	

Tab. 8

Tab.	9
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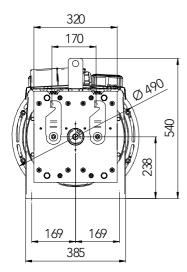
MGV34ML - Fig. 4					
Pul	ley	Ropes		Dimensions	
ØD	F	Ø	min max	Pitch	А
mm	mm	mm	n°	mm	mm
320		8	3 - 10	17	
400	180	10	5 - 10	17	153
480		12	3 - 9	20	155
520	145	13	3 - 7	20	

# Tab. 10

MGV34L - Fig. 5					
Pul	ley	Ropes		Dimensions	
ØD	F	Ø	min max	Pitch	А
mm	mm	mm	n°	mm	mm
320		8	3 - 10	17	
400	180	10	5 - 10	17	150
480		12	3 - 9	20	153
520	145	13	3 - 7	20	



Fig. 2 MGV34S



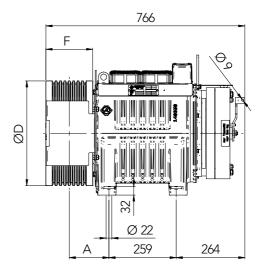
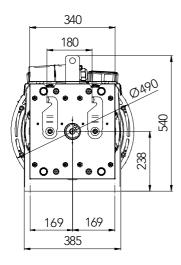
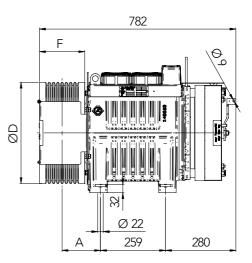
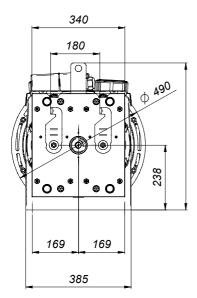


Fig. 3 MGV34M









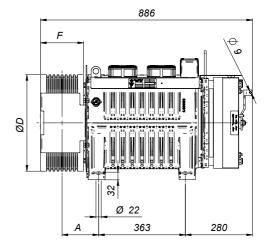
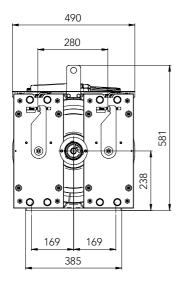
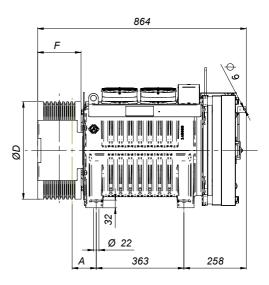


Fig. 5 MGV34L







## 3.3 Sound pressure

Tab. 11

MGV 34 RANGE / Sound pressure in dB(A)*				
Version	When operating	With brake		
S				
М	<48	<54		
ML	≦40	534		
L				



Only use lifting systems and equipment with adequate lifting capacity for handling. The entire packaging is designed to allow movement with forklift and forklift truck.

- 4. TRANSPORT AND STORAGE
- 4.1 Handling

All gearless machines are packed in crates or cages.

Different types of packaging can be used, depending on the size and means of transport. Unless otherwise specified, the packaging complies with the HPE guidelines.

In some cases, the machines are mounted on wooden pallets to enable them to be transported correctly on trucks. The packaging may not be stacked in any way. It is recommended to check the conditions of the material when it is received. In case of damage, do not proceed with the installation unless expressly authorized by Montanari Giulio & C. Observe the symbols on the packaging to prevent damage to property or personal injury. Here are the meanings of the symbols that may appear on the packaging.

Handle with care



Upper side

Keep dry



...

Fragile



Center of gravity

Do not use hooks



Attachment point



Keep away from heat sources





For lifting, anchor points (eyebolts) are provided as shown in Fig. 6. Use only the specified eyebolts to handle the unit.



### 4.2 Storage

The gearless machine must be stored in the position of use on a wooden base not subject to vibrations, in a covered and sheltered place.



If the unit is stored outdoors, it should be covered, taking care that no moisture and/or other foreign matter can accumulate on it.



Supplies for special environmental conditions during transport (e.g. by ship) and storage (climate, temperature, etc.) must be contractually agreed.



- Check the correct operation of the motor and brake after installation.
- Repairs may only be carried out by the manufacturer or by authorised per-
- sonnel.
  - The machine can be red-hot.
  - These machines must be connected to inverters.
- When the machine is rotating, both manually and mechanically, it can act as a generator and produce high voltage.
  - During configuration, the machine is powered by high voltage.



### 5. DESCRIPTION

### 5.1 General description

The MGV34 series gearless machines are permanent magnet motors with double brake system.

### 5.2 Main components

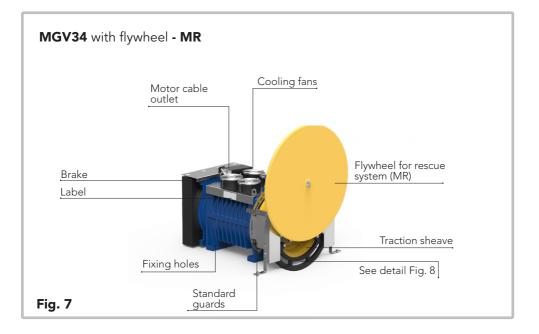
The unit consists of the main groups as shown in Fig. 7 - 8 - 9. For the versions with 400 - 480 - 520 mm sheave, it is possible to install the kit for the manual rescue system.

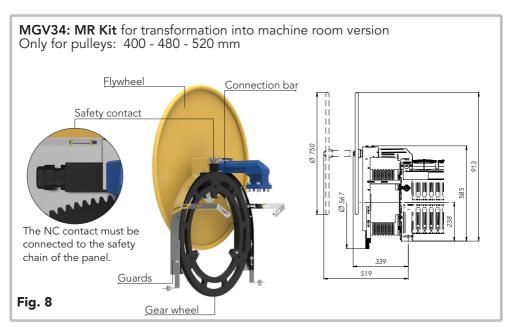
MGV34 S- M - ML - L are equipped with a PTC thermal probe inside the windings to protect against overheating (winding temperature up to 130°C) and with a thermo-contact for the activation of the fans. Refer to the electrical connections for more details. -  $\mathbb{P}^{2}$  See Par. 6.4.

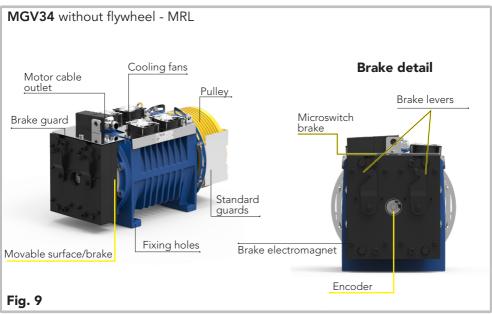
Lubrication



The gearless machine contains no oil and it is supplied with bearings already lubricated throughout the life of the machine; no further lubrication is required.









### 5.3 Brake

The gearless machine is supplied with a brake that conforms to the standards indicated in paragraph 2.5.

The brake system is pre-calibrated by the manufacturer and no further adjustment is required.



The brake system operates as follows:

• **Not powered** (electromagnet not powered): the brake disc is clamped by the movable surfaces (yellow arrows on Fig. 10). In this condition the system does not move.

• When the brake electromagnet is powered, it releases the brake disc (yellow arrows in Fig. 11); now the motor is released.



Brake system not powered



Brake system powered

### 6. INSTALLATION

6.1 General installation information



The gearless machine must be installed in a building or in a closed travel compartment.

Do not use the gearless machine in an explosive atmosphere.

The room temperature must be between 0°C and +40°C.

Assembly and installation must be carried out with great care by qualified and trained personnel.

The manufacturer cannot be held responsible for damage caused by incorrect assembly or incorrect installation.

Before starting work, make sure that adequate lifting and handling equipment is available.

No welding work must be carried out on the unit.

The unit must not be used as a grounding point for welding operations. The bearings can be irreparably damaged.

All fixing points specified by the manufacturer must be used.

The air supply for cooling must not be prevented.

### 6.2 Installation surface

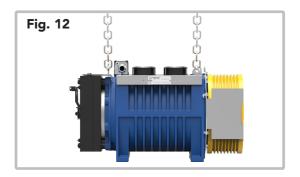
The installation surface must be uniform and level.

The levelling tolerance is 0.2 mm.

The installation surface must be rigid and robust enough to withstand the forces involved.

### 6.3 Installation procedure

The gearless machine can be lifted using the eyebolts for the insertion of the belts or lifting chains (see also the paragraph on storage and handling). Particular attention is needed to avoid that the gearless machine receives blows in correspondence of the brake disc; the brake levers and the electrical connections of the board are very delicate. Lifting example Fig. 12.





Place the unit on the installation surface and secure it.

- Fixing screws and nuts must be tightened to the prescribed torque.

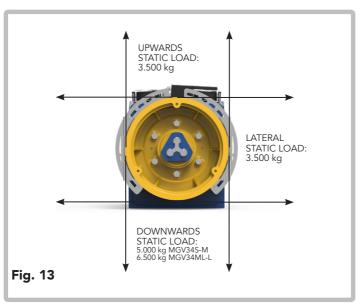
Use bolts with a minimum strength class of 8.8.
Do not force or hit the fixings to position them; this could damage the bearings, rings, etc.

• Mount the safety devices.

The gearless machines are suitable for use with and without the machine room. The static load changes depending on the roping direction. (Figure 13):

	Tab. 12			
Bolt tightening torques (class 8.8)				
(Class 0.0)				
Thread	M20			
Tightening torque (Nm)	410			

### Load direction

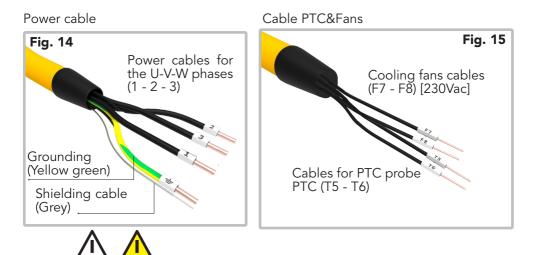


### 6.4 Electrical installation - Connections

The gearless machine is supplied with:

• power cable for the power supply of the motor [1 - 2 - 3, Ground, SC] (Fig. 17)

• cable for the power supply of the cooling fan (230 Vac).[F7-F8] and of the PTC guard [T5-T6] (Fig. 15).



- The power cable must be routed separately from the other cables.
- The motor power cable is shielded and the shield must be grounded.

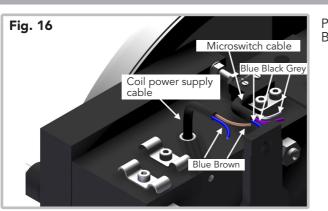
• The encoder cable must be routed away from the motor power cable to avoid electrical interference.

• The brake system has a power cable and another cable for the microswitch contacts. (Figure no. 16). All electrical data are listed on the label of the brake system. The microswitch has two contacts: one open and one closed. (Fig. 17).

• These contacts indicate the brake condition (see table 13).

100.15					
Brake disc	c closed	Condition contact	Brake	disc free	Condition contact
BLACK	BLUE	Disconnected	BLACK	BLUE	Connected
сом.	N.O.	Disconnected	сом//	N.O.	Connected
BLACK	GREY	Connected	BLACK		Disconnected
сом.	N.C.	Connected	COM.	N.C.	Disconnected

### Tab. 13



Power supply Brake

Below an example for setting the parallel connection of the brake coil.

### Standard mode:

It is possible controlling only contactor 1 and leaving contactors 2 and 3 closed. (Fig. 17).

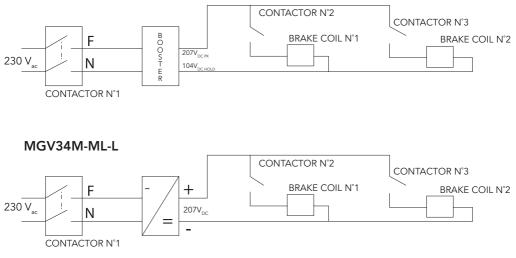
This protects the brake from dangerous overvoltage and noise when closing.

## - Emergency mode and inspection mode:

The use of all contactors is recommended. Using only contactor no. 1 during opening and/or closing operations may cause an unacceptable delay when closing the brake.







7. CONNECTION OF THE BRAKE FOR RESCUE SYSTEM

For installations with machine room, the cable and release lever are supplied as standard. The kit is shown in Fig. 18.



Connection cable for brake levers for manual rescue system (3.5 m).

7.1 Connection of the cable to the brake levers

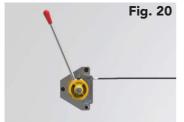
Insert the end of the cable into the lever holes. Tension and fix. Fold the end and secure with the rope clamp as shown in the figure. At the end, the result is as in the figure below. (Fig. 19).



Fig. 19



7.2 Connection of the cable to the hand release lever



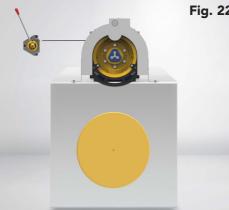
Fix the lever to the wall with the bolts (not supplied). Connect the cable to the support as shown in Fig. 20.

Insert the other end of the cable into the screw hole. Tighten to stop. Fig. 21

Fig. 21







**Fig. 22** Connection and installation must be carried out in such a way that the lever and the flywheel can be operated simultaneously. Fig. 22 - 23 - 24. This allows you to perform the rescue system operation correctly.

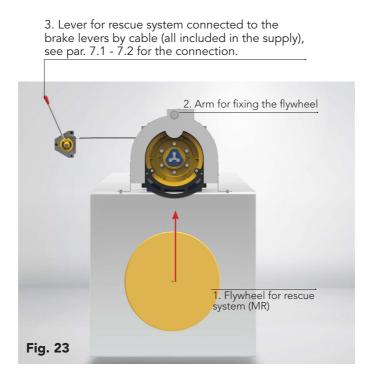
### 7.3 Rescue System

IMPORTANT: during normal operation the flywheel must not be installed; use the flywheel only to perform the emergency rescue system.

To slow down the car, it's recommended to connect the phases together (short circuited connection).

7.4 Manual rescue system

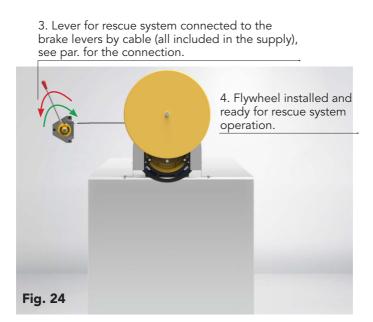
For installations with machine room



- 7.5 Procedure:
  - Stop the system

Calm any people inside the cab.
Remove the flywheel (1) from the hook and install it in the arm (2). The NC contact (Fig. 8) of the flywheel switch opens the supply circuit and ensures safe manual operation. The machine now looks like in Fig. 24.

* (NC = Normally Closed)



Grasp the flywheel firmly (4).

Operate lever (3) for manual brake release. Red arrow direction. Slowly turn the flywheel in the right direction to move the cab until the floor is reached.

Close the brake by releasing the lever: green arrow direction. Open the floor door and the cab door to free the people inside. Note: the company carrying out the maintenance of the lift system is responsible for these operations.

### 8. OPERATION

### 8.1 Connections

Connect the motor, brake, and monitoring devices.

The connection must be made by qualified personnel in accordance with the applicable safety regulations. Installation and operation requirements and current national and international standards must be met.

### 8.2 Additional components

If third party additional components or options are installed, please refer to the information in the respective separate documentation provided.

### 8.3 General operation information

When operating the MGV34 unit, be sure to check that the following situations do not occur:

- Excessive operating temperature.
- Excessive and unusual noise.

If any irregularity occurs during operation, turn off the power immediately. Identify the cause of the malfunction by using the table in Chap. 9, containing a list of possible problems, causes and suggested remedies.



If the cause of the malfunction cannot be identified, or if the unit has been repaired using the means available, you should contact one of our service centres for a specialised service

### 9. TROUBLESHOOTING, MAINTENANCE AND REPAIR

### 9.1 General information



Problems and malfunctions occurring during the warranty period, which are not precisely identified or which require work on the unit, must be referred to the manufacturer's Customer Service department.

Observe all safety rules.

Do not disassemble the motor on site.

The bearings are protected and do not require any additional lubrication under standard conditions of use.

Do not use high-pressure cleaners on the motor.

Montanari cannot guarantee or be held responsible for unauthorized operations on the unit, improper use, modifications made without its consent or the use of non-genuine spare parts.



When repairing problems or malfunctions, the unit must be put out of service in order to prevent unintentional start-up. Place a warning sign on the starting switch.



### 9.2 Traction/return sheave

Periodically, at least once a year, check the wear of the grooves in the traction sheave.

In case of slipping ropes or excessive wear, contact Montanari Giulio & C. for replacement instructions, always indicating the serial number.

### 9.3 Replacement of components

Instructions for the replacement of any component must be requested each time from the technical department specifying the serial number.

### 9.4 Problems, causes and solutions

Tab. 14

Diagnostic Table				
Problems	Causes	Solutions		
	Motor phases are connected in the wrong way	Check the connection condition of the motor phases		
	Wrong inverter configuration	Check the inverter settings		
	Inverter defective	Replace the device		
The motor does not work	Brake faulty	See below		
	Motor mechanically locked	Contact Montanari Giulio & C.		
	Motor connections loosened	Tighten the connections of the machine controller.		
	Excessive temperature	See below		
Brake system not working	Brake power supply wrong	Check the correct supply voltage of the brake coil.		
blake system not working	Brake system defective	Contact Montanari Giulio & C.		
	Cooling fan not working.	Replace the fan		
Excessive temperature	Cooling fan not correctly connected.	Check the voltage of the cooling fan. (230 V ac)		
	PTC sensor defective	Contact Montanari Giulio & C.		
	Wrong inverter settings	Check the inverter settings		
	Alignment of the motor with the deflection sheave incorrect.	Check and correct the alignment.		
Noise while travelling	Encoder defective	Replace encoder		
rioise while travening	Wrong inverter settings	Check the inverter settings		
	Bearing defective	Contact Montanari Giulio & C.		

- 9.5 Maintenance and repair
- 9.5.1 General indications



The unit must only be used, maintained and repaired by authorized, properly trained and qualified personnel.

Compliance with the inspection and maintenance intervals is part of the conditions for the validity of the warranty.

9.5.2 Description of maintenance activities

# Stop the unit and put it out of service. Place a warning sign on the start switch to prevent unintentional start.

Cleaning the unit Remove dirt on the unit with a hard brush. Remove corrosion signs. The unit must not be cleaned with high pressure washing equipment.

Checking the tightening of bolts and nuts

Checking the tightening of all fastening bolts and nuts with a torque wrench. The screws and nuts must be tightened to the prescribed torque. The tightening torque is indicated in Table 15.

	Tab. 15			
Tightening torque (classe 8.8)				
Thread	M20			
tightening torque (Nm)	410			



10. SPARE PARTS

10.1 General information



By keeping the main spare parts and wear parts in stock, the unit can  $\mathbf{V}_{\top | \mathcal{P}}$  always be used.

### 10.2 How to order spare parts

The manufacturer guarantees only genuine spare parts and accessories supplied by him.

Other parts not supplied by the manufacturer have not been tested or approved. The use of these parts can therefore compromise certain characteristics of the gearless machine and expose it to active and passive safety risks.



The manufacturer will not assume any responsibility and will not recognize warranty for damage caused by spare parts and accessories not supplied by the manufacturer himself.

When ordering spare parts, always specify:

- Order no. of the machine to which they must be applied;
- Part code;
- Description;
- Quantity;

To order spare parts, write to **service@montanarigiulio.com.** 

### 11. COMPLIANCE DECLARATION



### MONTANARI GIULIO & C. S.r.I.

COMPLIANCE DECLARATION GEARLESS

### Manufacturer: Montanari Giulio & C. S.r.l. Via Bulgaria n.39, 41122 Modena

Models concerned by the current declaration:

MGX19 – MGV19 – MSG19M – MGS19L – MGV20M – MGV20L – MG200.3 – MGX21 – MGV25S – MGV25M – MGV25ML – MGV25L – MGV34 – MGV34S – MGV34M – MGV34ML – MGV34L – MGV34.4 – MG345.6 – MGV34.6 – MGX75 – MGX80 – MDD035 – MDD070 – MGV30.4 – MGV30.6 – MGX53 – MGX53S.

It is stated that the gearless in guestion comply with the Machines Directive 2006/42/CE as regards its relevant aspects and meets the following essential safety requirements as set out in Annex 1 of the directive:

- 1.3.2 risk of damage during the functioning;
- 1.5.1 electricity;
- 1.5.4 assembly errors;
- 1.5.8 noise;
- 1.5.9 vibration;
- 1.6 maintenance; 1.7.4 instructions.

The related technical documentation has been drafted in compliance with the Annex VII B.

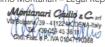
Therefore, it complies with the following directives: - 2014/33/UE, 2014/30/UE, 2014/35/UE

- 2014/33/0E, 2014/39/0E, 2014/39/0E, 2014/39/0E In addition, with the following regulations: UNI 10411-1; UNI 10411-3; UNI 10411-5; UNI EN 81-1:2010; UNI EN 81-20:2014

Note:

As regards, the fulfillment of the paragraph 9.7 of the UNI EN81-1:2010 and 5.5.7 UNI EN81-20:2014, it is recalled that Montanari provides safety device only upon explicit request by the customer.

Drafting: Stefano Bertoni – Technical Director Signature: Massimo Montanari - Legal Representative



Modena, il 20/03/2020

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